Loss modeling features of actuar

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1 Introduction

One important task of actuaries is the modeling of claim amount and claim count distributions for ratemaking, loss reserving or other risk evaluation purposes. Package **actuar** features many support functions for loss distributions modeling:

- 1. support for heavy tail continuous distributions useful in loss severity modeling;
- 2. support for phase-type distributions for ruin theory;
- 3. functions to compute raw moments, limited moments and the moment generating function (when it exists) of continuous distributions;
- 4. support for zero-truncated and zero-modified extensions of the discrete distributions commonly used in loss frequency modeling;
- 5. extensive support of grouped data;
- 6. functions to compute empirical raw and limited moments;
- 7. support for minimum distance estimation using three different measures;
- 8. treatment of coverage modifications (deductibles, limits, inflation, coinsurance).

Vignette "distributions" covers the points 1–4 above in great detail. This document concentrates on points 5–8.

2 Grouped data

Grouped data is data represented in an interval-frequency manner. Typically, a grouped data set will report that there were n_j claims in the interval $(c_{j-1}, c_j]$, $j=1,\ldots,r$ (with the possibility that $c_r=\infty$). This representation is much more compact than an individual data set — where the value of each claim is known — but it also carries far less information. Now that storage space in computers has essentially become a non issue, grouped data has somewhat fallen out of fashion. Still, grouped data remains useful as a means to represent data, if only graphically — for example, a histogram is nothing but a density approximation for grouped data. Moreover, various parameter estimation techniques rely on grouped data.

For these reasons, **actuar** provides facilities to store, manipulate and summarize grouped data. A standard storage method is needed since there are many ways to represent grouped data in the computer: using a list or a matrix, aligning n_j with c_{j-1} or with c_j , omitting c_0 or not, etc. With appropriate extraction, replacement and summary methods, manipulation of grouped data becomes similar to that of individual data.

Function grouped.data creates a grouped data object similar to — and inheriting from — a data frame. The function accepts two types of input:

- 1. a vector of group boundaries c_0, c_1, \ldots, c_r and one or more vectors of group frequencies n_1, \ldots, n_r (note that there should be one more group boundary than group frequencies);
- 2. individual data $x_1, ..., x_n$ and either a vector of breakpoints $c_1, ..., c_r$, a number r of breakpoints or an algorithm to determine the latter.

In the second case, grouped data will group the individual data using function hist. The function always assumes that the intervals are contiguous.

Example 1. Consider the following already grouped data set:

Group	Frequency (Line 1)	Frequency (Line 2)
(0, 25]	30	26
(25,50]	31	33
(50, 100]	57	31
(100, 150]	42	19
(150, 250]	65	16
(250, 500]	84	11

We can conveniently and unambiguously store this data set in R as follows:

Internally, object x is a list with class

```
> class(x)
[1] "grouped.data" "data.frame"
```

The package provides a suitable print method to display grouped data objects in an intuitive manner:

```
> x

Group Line.1 Line.2

1 (0, 25] 30 26

2 (25, 50] 31 33

3 (50, 100] 57 31

4 (100, 150] 42 19

5 (150, 250] 65 16

6 (250, 500] 84 11
```

Example 2. Consider Data Set B of Klugman et al. (2012, Table 11.2):

```
27
      82
                 126
                      155
                                     243
                                             294
                                                    340
                                                            384
           115
                              161
457
     680
           855
                 877
                      974
                            1,193
                                   1,340
                                          1,884
                                                  2,558
                                                         15,743
```

We can represent this data set as grouped data using either an automatic or a suggested number of groups (see ?hist for details):

```
> y < - c(27,
                 82, 115,
                             126, 155, 161, 243, 294,
                           680, 855, 877, 974, 1193,
          340, 384, 457,
         1340, 1884, 2558, 15743)
                                          # automatic
 grouped.data(y)
           2000] 18
   (2000,
           4000]
   (4000,
           6000]
   (6000,
           8000]
   (8000, 10000]
 (10000, 12000]
7 (12000, 14000]
 (14000, 16000]
 grouped.data(y, breaks = 5)
                                          # suggested
           5000] 19
   (5000, 10000]
 (10000, 15000]
4 (15000, 20000]
```

The above grouping methods use equi-spaced breaks. This is rarely appropriate for heavily skewed insurance data. For this reason, grouped.data also supports specified breakpoints (or group boundaries):

The package supports the most common extraction and replacement methods for "grouped.data" objects using the usual [and [<- operators. In particular, the following extraction operations are supported. (In the following, object x is the grouped data object of example 1.)

i) Extraction of the vector of group boundaries (the first column):

```
> x[, 1] # group boundaries
[1] 0 25 50 100 150 250 500
```

ii) Extraction of the vector or matrix of group frequencies (the second and third columns):

iii) Extraction of a subset of the whole object (first three lines):

```
> x[1:3, ] # first 3 groups

Group Line.1 Line.2
1 (0, 25] 30 26
2 (25, 50] 31 33
3 (50, 100] 57 31
```

Notice how extraction results in a simple vector or matrix if either of the group boundaries or the group frequencies are dropped.

As for replacement operations, the package implements the following.

i) Replacement of one or more group frequencies:

ii) Replacement of the boundaries of one or more groups:

It is not possible to replace the boundaries and the frequencies simultaneously. The mean of grouped data is

$$\hat{\mu} = \frac{1}{n} \sum_{j=1}^{r} a_j n_j,\tag{1}$$

where $a_j = (c_{j-1} + c_j)/2$ is the midpoint of the jth interval, and $n = \sum_{j=1}^r n_j$, whereas the variance is

$$\frac{1}{n} \sum_{j=1}^{r} n_j (a_j - \hat{\mu})^2.$$
 (2)

The standard deviation is the square root of the variance. The package defines methods to easily compute the above descriptive statistics:

```
> mean(x)
Line.1 Line.2
188.0 108.2
> var(x)
Line.1 Line.2
25050 14945
> sd(x)
Line.1 Line.2
158.3 122.3
```

Higher empirical moments can be computed with emm; see section 4.

The R function hist splits individual data into groups and draws an histogram of the frequency distribution. The package introduces a method for already grouped data. Only the first frequencies column is considered (see Figure 1 for the resulting graph):

```
> hist(x[, -3])
```

Remark 1. One will note that for an individual data set like y of example 2, the following two expressions yield the same result:

```
> hist(y)  # histogram method for individual data
> hist(grouped.data(y)) # histogram method for grouped data
```

R has a function ecdf to compute the empirical cdf $F_n(x)$ of an individual data set:

$$F_n(x) = \frac{1}{n} \sum_{i=1}^n I\{x_j \le x\},\tag{3}$$

where $I\{A\} = 1$ if A is true and $I\{A\} = 0$ otherwise. The function returns a "function" object to compute the value of $F_n(x)$ in any x.

The approximation of the empirical cdf for grouped data is called an ogive (Klugman et al., 2012; Hogg and Klugman, 1984). It is obtained by joining the known values of $F_n(x)$ at group boundaries with straight line segments:

$$\tilde{F}_n(x) = \begin{cases}
0, & x \le c_0 \\
\frac{(c_j - x)F_n(c_{j-1}) + (x - c_{j-1})F_n(c_j)}{c_j - c_{j-1}}, & c_{j-1} < x \le c_j \\
1, & x > c_r.
\end{cases}$$
(4)

Histogram of c(0, 20, 55, 110, 160, 250, 500)

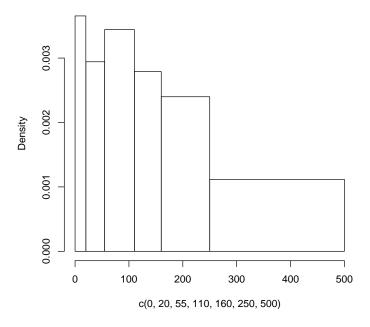


Figure 1: Histogram of a grouped data object

The package includes a generic function ogive with methods for individual and for grouped data. The function behaves exactly like ecdf.

Example 3. Consider first the grouped data set of example 1. Function ogive returns a function to compute the ogive $\tilde{F}_n(x)$ in any point:

```
> (Fnt <- ogive(x))
Ogive for grouped data
Call: ogive(x = x)
    x = 0, 20, 55, ..., 2.5e+02, 5e+02
F(x) = 0, 0.073, 0.18, ..., 0.72, 1</pre>
```

Methods for functions knots and plot allow, respectively, to obtain the knots c_0, c_1, \ldots, c_r of the ogive and to draw a graph (see Figure 2):

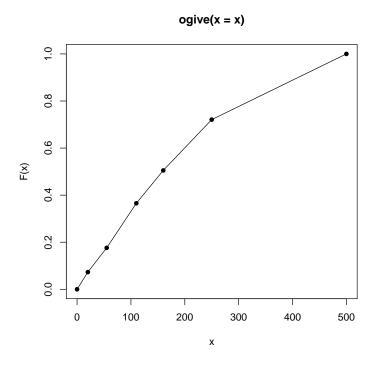


Figure 2: Ogive of a grouped data object

```
> plot(Fnt) # plot of the ogive
```

To add further symmetry between functions hist and ogive, the latter also accepts in argument a vector individual data. It will call grouped data and then computes the ogive. (Below, y is the individual data set of example 2.)

```
> (Fnt <- ogive(y))
Ogive for grouped data
Call: ogive(x = y)
    x = 0, 2e+03, 4e+03, ..., 1.4e+04, 1.6e+04
F(x) = 0, 0.9, 0.95, ..., 0.95, 1
> knots(Fnt)
[1]    0  2000  4000  6000  8000  10000  12000  14000
[9] 16000
```

A method of function quantile for grouped data objects returns linearly smoothed quantiles, that is, the inverse of the ogive evaluated at various points:

```
> quantile(x)
    0% 25% 50% 75% 100%
    0.00 76.47 158.21 276.04 500.00
> Fnt(quantile(x))
[1] 0.00 0.25 0.50 0.75 1.00
```

Finally, a summary method for grouped data objects returns the quantiles and the mean, as is usual for individual data:

```
> summary(x)
Min. 1st Qu. Median Mean 3rd Qu. Max.
0.0 76.5 158.2 188.0 276.0 500.0
```

3 Data sets

This is certainly not the most spectacular feature of **actuar**, but it remains useful for illustrations and examples: the package includes the individual dental claims and grouped dental claims data of Klugman et al. (2012):

```
> data("dental"); dental
 [1] 141
            16 46
                          351 259 317 1511 107
[10] 567
> data("gdental"); gdental
             cj nj
            25] 30
     (25,
           50] 31
     (50, 100] 57
     (100, 150] 42
     (150, 250] 65
     (250, 500] 84
    (500, 1000] 45
   (1000, 1500] 10
   (1500, 2500] 11
10 (2500, 4000]
```

4 Calculation of empirical moments

The package provides two functions useful for estimation based on moments. First, function emm computes the kth empirical moment of a sample, whether in individual or grouped data form:

```
> emm(dental, order = 1:3)  # first three moments

[1] 3.355e+02 2.931e+05 3.729e+08

> emm(gdental, order = 1:3)  # idem
```

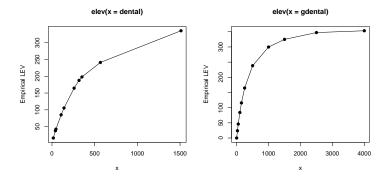


Figure 3: Empirical limited expected value function of an individual data object (left) and a grouped data object (right)

[1] 3.533e+02 3.577e+05 6.586e+08

Second, in the same spirit as ecdf and ogive, function elev returns a function to compute the empirical limited expected value — or first limited moment — of a sample for any limit. Again, there are methods for individual and grouped data (see Figure 3 for the graphs):

5 Minimum distance estimation

Two methods are widely used by actuaries to fit models to data: maximum likelihood and minimum distance. The first technique applied to individual data is well covered by function fitdistr of the package **MASS** (Venables and Ripley, 2002).

The second technique minimizes a chosen distance function between theoretical and empirical distributions. Package **actuar** provides function mde, very similar in usage and inner working to fitdistr, to fit models according to any of the following three distance minimization methods.

1. The Cramér-von Mises method (CvM) minimizes the squared difference between the theoretical cdf and the empirical cdf or ogive at their knots:

$$d(\theta) = \sum_{j=1}^{n} w_j [F(x_j; \theta) - F_n(x_j; \theta)]^2$$
 (5)

for individual data and

$$d(\theta) = \sum_{i=1}^{r} w_j [F(c_j; \theta) - \tilde{F}_n(c_j; \theta)]^2$$
 (6)

for grouped data. Here, F(x) is the theoretical cdf of a parametric family, $F_n(x)$ is the empirical cdf, $\tilde{F}_n(x)$ is the ogive and $w_1 \geq 0, w_2 \geq 0, \ldots$ are arbitrary weights (defaulting to 1).

2. The modified chi-square method (chi-square) applies to grouped data only and minimizes the squared difference between the expected and observed frequency within each group:

$$d(\theta) = \sum_{j=1}^{r} w_j [n(F(c_j; \theta) - F(c_{j-1}; \theta)) - n_j]^2, \tag{7}$$

where $n = \sum_{j=1}^{r} n_j$. By default, $w_j = n_j^{-1}$.

3. The layer average severity method (LAS) applies to grouped data only and minimizes the squared difference between the theoretical and empirical limited expected value within each group:

$$d(\theta) = \sum_{i=1}^{r} w_{j} [LAS(c_{j-1}, c_{j}; \theta) - L\tilde{A}S_{n}(c_{j-1}, c_{j}; \theta)]^{2},$$
(8)

where LAS(x,y) = $E[X \land y] - E[X \land x]$, LÃS_n(x,y) = $\tilde{E}_n[X \land y] - \tilde{E}_n[X \land x]$ and $\tilde{E}_n[X \land x]$ is the empirical limited expected value for grouped data.

The arguments of mde are a data set, a function to compute F(x) or $E[X \wedge x]$, starting values for the optimization procedure and the name of the method to use. The empirical functions are computed with ecdf, ogive or elev.

Example 4. The expressions below fit an exponential distribution to the grouped dental data set, as per example 2.21 of Klugman et al. (1998):

```
> mde(gdental, pexp, start = list(rate = 1/200),
+    measure = "CvM")
    rate
    0.003551

distance
    0.002842
```

It should be noted that optimization is not always as simple to achieve as in example 4. For example, consider the problem of fitting a Pareto distribution to the same data set using the Cramér–von Mises method:

```
> mde(gdental, ppareto, start = list(shape = 3, scale = 600),
+ measure = "CvM") # no convergence

Error in mde(gdental, ppareto, start = list(shape = 3, scale = 600),
```

measure = "CvM") :

l'optimisation a échoué

Working in the log of the parameters often solves the problem since the optimization routine can then flawlessly work with negative parameter values:

The actual estimators of the parameters are obtained with

```
> exp(p$estimate)
logshape logscale
   4.861 1246.485
```

This procedure may introduce additional bias in the estimators, though.

Coverage modification	Per-loss variable (Y^L)	Per-payment variable (Y ^P)
Ordinary deductible (d)	$\begin{cases} 0, & X \le d \\ X - d, & X > d \end{cases}$	X - d, X > d
Franchise deductible (<i>d</i>)	$\begin{cases} 0, & X \le d \\ X, & X > d \end{cases}$	X, X > d
Limit (u)	$\begin{cases} X, & X \le u \\ u, & X > u \end{cases}$	$\begin{cases} X, & X \le u \\ u, & X > u \end{cases}$
Coinsurance (α)	αX	αX
Inflation (r)	(1+r)X	(1+r)X

Table 1: Coverage modifications for per-loss variable (Y^L) and per-payment variable (Y^P) as defined in Klugman et al. (2012).

6 Coverage modifications

Let X be the random variable of the actual claim amount for an insurance policy, Y^L be the random variable of the amount paid per loss and Y^P be the random variable of the amount paid per payment. The terminology for the last two random variables refers to whether or not the insurer knows that a loss occurred. Now, the random variables X, Y^L and Y^P will differ if any of the following coverage modifications are present for the policy: an ordinary or a franchise deductible, a limit, coinsurance or inflation adjustment (see Klugman et al., 2012, chapter 8 for precise definitions of these terms). Table 1 summarizes the definitions of Y^L and Y^P .

Often, one will want to use data Y_1^P, \ldots, Y_n^P (or Y_1^L, \ldots, Y_n^L) from the random variable Y^P (Y^L) to fit a model on the unobservable random variable X. This requires expressing the pdf or cdf of Y^P (Y^L) in terms of the pdf or cdf of X. Function coverage of **actuar** does just that: given a pdf or cdf and any combination of the coverage modifications mentioned above, coverage returns a function object to compute the pdf or cdf of the modified random variable. The function can then be used in modeling like any other dfoo or pfoo function.

Example 5. Let Y^P represent the amount paid by an insurer for a policy with an ordinary deductible d and a limit u - d (or maximum covered loss of u). Then the definition of Y^P is

$$Y^{P} = \begin{cases} X - d, & d \le X \le u \\ u - d, & X \ge u \end{cases} \tag{9}$$

and its pdf is

$$f_{Y^{P}}(y) = \begin{cases} 0, & y = 0\\ \frac{f_{X}(y+d)}{1 - F_{X}(d)}, & 0 < y < u - d\\ \frac{1 - F_{X}(u)}{1 - F_{X}(d)}, & y = u - d\\ 0, & y > u - d. \end{cases}$$
(10)

Assume *X* has a gamma distribution. Then an R function to compute the pdf (10) in any y for a deductible d=1 and a limit u=10 is obtained with coverage as follows:

```
> f <- coverage(pdf = dgamma, cdf = pgamma,</pre>
                      deductible = 1, limit = 10)
  function (x, shape, rate = 1, scale = 1/rate)
       Call <- match.call()</pre>
       Sd <- Call
       Sd$lower.tail <- FALSE
       Sd[[1L]] <- as.name("pgamma")</pre>
       names(Sd)[2L] \leftarrow "q"
       Sd[[2L]] <- 1
       Su <- Sd
       Su[[2L]] <- 10
       f <- Call
       f[[1L]] <- as.name("dgamma")</pre>
       res <- numeric(length(x))</pre>
       w <- which(0 < x & x < 9)
       f[[2L]] <- x[w] + 1
       res[w] <- eval.parent(f)/(p <- eval.parent(Sd))</pre>
       res[x == 9] \leftarrow eval.parent(Su)/p
  <environment: 0x7fc8027734f8>
  > f(0, shape = 5, rate = 1)
[1] 0
> f(5, shape = 5, rate = 1)
[1] 0.1343
> f(9, shape = 5, rate = 1)
[1] 0.02936
> f(12, shape = 5, rate = 1)
[1] 0
```

Note how function f in the previous example is built specifically for the coverage modifications submitted and contains as little useless code as possible.

The function returned by coverage may be used for various purposes, most notably parameter estimation, as the following example illustrates.

Example 6. Let object y contain a sample of claims amounts from policies with the deductible and limit of example 5. One can fit a gamma distribution by maximum likelihood to the claim severity distribution as follows:

```
> library(MASS)
> fitdistr(y, f, start = list(shape = 2, rate = 0.5))
    shape     rate
    4.6626    0.8690
    (0.7497) (0.1460)
```

Vignette "coverage" contains more detailed formulas for the pdf and the cdf under various combinations of coverage modifications.

References

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