

# Package ‘approximator’

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**Type** Package

**Title** Bayesian Prediction of Complex Computer Codes

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**Author** Robin K. S. Hankin

**Depends** R (>= 2.0.0), emulator (>= 1.2-11)

**Imports** mvtnorm

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**Description** Performs Bayesian prediction of complex computer codes when fast approximations are available. It uses a hierarchical version of the Gaussian process, originally proposed by Kennedy and O’Hagan (2000), *Biometrika* 87(1):1.

**License** GPL-2

**NeedsCompilation** no

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approximator-package    *Bayesian approximation of computer models when fast approximations are available*

---

## Description

Implements the ideas of Kennedy and O’Hagan 2000 (see references).

## Details

Package: approximator  
 Type: Package  
 Version: 1.0  
 Date: 2006-01-10  
 License: GPL

This package implements the Bayesian approximation techniques discussed in Kennedy and O’Hagan 2000.

In its simplest form, it takes input from a “slow” but accurate code and a “fast” but inaccurate code, each run at different points in parameter space. The approximator package then uses both sets of model runs to infer what the slow code would produce at a given, untried point in parameter space.

The package includes functionality to work with a hierarchy of codes with increasing accuracy.

## Author(s)

Robin K. S. Hankin

Maintainer: <hankin.robin@gmail.com>

## References

R. K. S. Hankin 2005. “Introducing BACCO, an R bundle for Bayesian analysis of computer code output”, *Journal of Statistical Software*, 14(16)

M. C. Kennedy and A. O’Hagan 2000. “Predicting the output from a complex computer code when fast approximations are available” *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
mdash.fun(x=1:3, D1=D1.toy, subsets=subsets.toy, hpa=hpa.toy, z=z.toy, basis=basis.toy)
```

---

Afun

*Matrix of correlations between two sets of points*

---

**Description**

Returns the matrix of correlations of code output at each level evaluated at points on the design matrix.

**Usage**

```
Afun(level, Di, Dj, hpa)
```

**Arguments**

level	The level. This enters via the correlation scales
Di	First set of points
Dj	Second set of points
hpa	Hyperparameter object

**Details**

This is essentially a convenient wrapper for function `corr.matrix`. It is not really intended for the end user.

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**See Also**

[corr,c\\_fun](#)

## Examples

```
data(toyapps)
D2 <- D1.toy[subsets.toy[[2]],]
D3 <- D1.toy[subsets.toy[[3]],]

Afun(1,D2,D3,hpa.toy)
Afun(2,D2,D3,hpa.toy)
```

---

as.sublist	<i>Converts a level one design matrix and a subsets object into a list of design matrices, one for each level</i>
------------	---

---

## Description

Given a level one design matrix, and a subsets object, convert into a list of design matrices, each one of which is the design matrix for its own level

## Usage

```
as.sublist(D1, subsets)
```

## Arguments

D1	Design matrix for level one code
subsets	subsets object

## Author(s)

Robin K. S. Hankin

## References

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

## Examples

```
data(toyapps)
as.sublist(D1=D1.toy , subsets=subsets.toy)
```

---

`basis.toy`*Toy basis functions*

---

**Description**

A working example of a basis function

**Usage**

```
basis.toy(x)
```

**Arguments**

`x` Point in parameter space

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
basis.toy(D1.toy)
```

---

`betahat.app`*Estimate for beta*

---

**Description**

Returns the estimator for beta; equation 5. Function `betahat.app()` returns the estimate in terms of fundamental variables; `betahat.app.H()` requires the H matrix.

**Usage**

```
betahat.app.H(H, V = NULL, Vinv = NULL, z)
betahat.app(D1, subsets, basis, hpa, z, use.Vinv=TRUE)
```

**Arguments**

H	In <code>betahat.app.H()</code> , the H matrix, eg that returned by <code>H.fun()</code>
V	Variance matrix
Vinv	Inverse of variance matrix. If not supplied, it is calculated
use.Vinv	In function <code>betahat.app()</code> , a Boolean argument with default TRUE meaning to calculate the inverse of the V matrix; and FALSE meaning to use a method which does not involve calculating the inverse of V. The default method seems to be faster; YMMV
z	vector of observations
D1	Design matrix for level 1 code
subsets	Subsets object
basis	Basis function
hpa	Hyperparameter object

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)

betahat.app(D1=D1.toy, subsets=subsets.toy, basis=basis.toy, hpa=hpa.toy, z=z.toy, use.Vinv=TRUE)

H <- H.fun.app(D1=D1.toy, subsets=subsets.toy, basis=basis.toy, hpa=hpa.toy)
V <- V.fun.app(D1=D1.toy, subsets=subsets.toy, hpa=hpa.toy)
betahat.app.H(H=H, V=V, z=z.toy)
```

---

c.fun

*Correlations between points in parameter space*

---

**Description**

Correlation matrices between (sets of) points in parameter space, both prior (`c_fun()`) and posterior (`cdash.fun()`).

**Usage**

```
c_fun(x, xdash=x, subsets, hpa)
cdash.fun(x, xdash=x, V=NULL, Vinv=NULL, D1, subsets, basis, hpa, method=2)
```

**Arguments**

x,xdash	Points in parameter space; or, if a matrix, interpret the rows as points in parameter space. Note that the default value of xdash (viz x) will return the variance-covariance matrix of a set of points
D1	Design matrix
subsets	Subset object
hpa	hyperparameter object
basis	Basis function
V,Vinv	In function cdash.fun(), the data covariance matrix and its inverse. If NULL, the matrix will be calculated from scratch. Supplying a precalculated value for V, and especially Vinv, makes for very much faster execution (depending on method)
method	Integer specifying which of several algebraically identical methods to use. See the source code for details, but default option 2 seems to be the best. Bear in mind that option 3 does not require inversion of a matrix, but is not faster in practice

**Value**

Returns a matrix of covariances

**Note**

Do not confuse function c\_fun(), which computes  $c(x, x')$  defined just below equation 7 on page 4 with  $c_t(x, x')$  defined in equation 3 on page 3.

Consider the example given for two levels on page 4 just after equation 7:  $c(x, x') = c_2(x, x') + \rho_1^2 c_1(x, x')$  is a kind of prior covariance matrix. Matrix  $c'(x, x')$  is a posterior covariance matrix, conditional on the code observations.

Function Afun() evaluates  $c_t(x, x')$  in a nice vectorized way.

Equation 7 of KOH2000 contains a typo.

**Author(s)**

Robin K. S. Hankin

**References**

KOH2000

**See Also**

[Afun](#)

**Examples**

```

data(toyapps)

x <- latin.hypercube(4,3)
rownames(x) <- c("ash", "elm", "oak", "pine")
xdash <- latin.hypercube(7,3)
rownames(xdash) <- c("cod","bream","skate","sole","eel","crab","squid")

cdash.fun(x=x,xdash=xdash, D1=D1.toy, basis=basis.toy,subsets=subsets.toy, hpa=hpa.toy)

# Now add a point whose top-level value is known:
x <- rbind(x,D1.toy[subsets.toy[[4]][1],])

cdash.fun(x=x,xdash=xdash, D1=D1.toy, basis=basis.toy,subsets=subsets.toy, hpa=hpa.toy)
# Observe how the bottom row is zero (up to rounding error)

```

---

```
generate.toy.observations
```

*Er, generate toy observations*

---

**Description**

Generates toy observations on four levels using either internal (unknown) parameters and hyperparameters, or user-supplied versions.

**Usage**

```
generate.toy.observations(D1, subsets, basis.fun, hpa = NULL, betas = NULL,
export.truth = FALSE)
```

**Arguments**

D1	Design matrix for level 1 code
subsets	Subset object
basis.fun	Basis function
hpa	Hyperparameter object. If NULL, use the internal (true but unknown) hyperparameter object
betas	Regression coefficients. If NULL, use the internal (true but unknown) regression coefficients
export.truth	Boolean, with default FALSE meaning to return synthetic observations and TRUE meaning to return the actual hyperparameters and coefficients.

**Author(s)**

Robin K. S. Hankin



## References

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

## Examples

```
data(toyapps)
generate.toy.observations(D1=D1.toy, subsets=subsets.toy, basis.fun=basis.toy)
```

---

genie

*Genie datasets for approximator package*

---

## Description

Genie datasets that illustrate the package.

## Usage

```
data(genie)
D1.genie
hpa.genie
z.genie
subsets.genie
basis.genie(x)
hpa.fun.genie(x)
hpa.genie.start
hpa.genie.optimal
```

## Arguments

`x` A 4-element vector (for `basis.genie()`); a 19-element vector (for `hpa.fun.genie()`)

## Format

The `genie` example is a case with three levels.

The `D1.genie` matrix is 36 rows of code run points, corresponding to the observations of the level 1 code. It has four columns, one per parameter.

`hpa.genie` is a hyperparameter object.

`subsets.genie` is a list of three elements. Element  $i$  corresponds to the rows of `D1.genie` at which level  $i$  has been observed.

`z.genie` is a three element list. Each element is a vector; element  $i$  corresponds to observations of level  $i$ . The lengths will match those of `subsets.genie`.

Function `basis.genie()` is a suitable basis function.

Function `hpa.fun.genie()` creates a hyperparameter object in a form suitable for passing to the other functions in the library.

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(genie)
z.genie

jj <- list(trace=100,maxit=10)

hpa.genie.level1 <- opt.1(D=D1.genie, z=z.genie,
                        basis=basis.genie, subsets=subsets.genie,
                        hpa.start=hpa.genie.start,control=jj)

hpa.genie.level2 <- opt.gt.1(level=2, D=D1.genie, z=z.genie,
                             basis=basis.genie, subsets=subsets.genie,
                             hpa.start=hpa.genie.level1,control=jj)

hpa.genie.level3 <- opt.gt.1(level=3, D=D1.genie, z=z.genie,
                             basis=basis.genie, subsets=subsets.genie,
                             hpa.start=hpa.genie.level2,control=jj)
```

---

H.fun

*The H matrix*

---

**Description**

Returns the matrix of bases H. The "app" of the function name means "approximator", to distinguish it from function H.fun() of the calibrator package.

**Usage**

```
H.fun.app(D1, subsets, basis, hpa)
```

**Arguments**

D1	Design matrix for level 1 code
subsets	Subsets object
basis	Basis function
hpa	Hyperparameter object

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
H.fun.app(D1.toy , subsets=subsets.toy , basis=basis.toy , hpa=hpa.toy)
```

---

hdash.fun

*Hdash*

---

**Description**

Returns the thing at the top of page 6

**Usage**

```
hdash.fun(x, hpa, basis)
```

**Arguments**

x	Point in question
hpa	Hyperparameter object
basis	Basis functions

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
hdash.fun(x=1:3 , hpa=hpa.toy,basis=basis.toy)

uu <- rbind(1:3,1,1:3,3:1)
rownames(uu) <- paste("uu",1:4,sep="_")
hdash.fun(x=uu, hpa=hpa.toy,basis=basis.toy)
```

---

`hpa.fun.toy`*Toy example of a hyperparameter object creation function*

---

**Description**

Creates a hyperparameter object from a vector of length 19. Intended as a toy example to be modified for real-world cases.

**Usage**

```
hpa.fun.toy(x)
```

**Arguments**

`x` Vector of length 19 that specifies the correlation scales

**Details**

Elements 1-4 of `x` specify the sigmas for each of the four levels in the toy example. Elements 5-7 specify the correlation scales for level 1, elements 8-10 the scales for level 2, and so on.

Internal function `pdm.maker()` shows how the `B` matrix is obtained from the various elements of input argument `x`. Note how, in this simple example, the `B` matrices are diagonal, but generalizing to non-diagonal matrices should be straightforward (if you can guarantee that they remain positive definite).

**Value**

<code>sigmas</code>	The four sigmas corresponding to the four levels
<code>B</code>	The four <code>B</code> matrices corresponding to the four levels
<code>rhos</code>	The three (sic) matrices corresponding to levels 1-3

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
hpa.fun.toy(1:19)
```

---

is.consistent	<i>Checks observational data for consistency with a subsets object</i>
---------------	--

---

**Description**

Checks observational data for consistency with a subsets object: the length of the vectors should match

**Usage**

```
is.consistent(subsets, z)
```

**Arguments**

subsets	A subsets object
z	Data

**Value**

Returns TRUE or FALSE depending on whether z is consistent with subsets.

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**See Also**

[is.nested](#)

**Examples**

```
data(toyapps)
stopifnot(is.consistent(subsets.toy,z.toy))

z.toy[[4]] <- 1:6
is.consistent(subsets.toy,z.toy)
```

---

 mdash.fun

*Mean of Gaussian process*


---

**Description**

Returns the mean of the Gaussian process conditional on the observations and the hyperparameters

**Usage**

```
mdash.fun(x, D1, subsets, hpa, Vinv = NULL, use.Vinv = TRUE, z, basis)
```

**Arguments**

x	Point at which mean is desired
D1	Code design matrix for level 1 code
subsets	subsets object
hpa	Hyperparameter object
Vinv	Inverse of the variance matrix; if NULL, the function will calculate it
use.Vinv	Boolean, with default TRUE meaning to use the inverse of V and FALSE meaning to use a method that does not involve inverting V
z	observations
basis	Basis functions

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
mdash.fun(x=1:3,D1=D1.toy,subsets=subsets.toy,hpa=hpa.toy,z=z.toy,basis=basis.toy)

uu <- rbind(1:3,1,3:1,1:3)
rownames(uu) <- c("first","second","third","fourth")

mdash.fun(x=uu,D1=D1.toy,subsets=subsets.toy,hpa=hpa.toy,z=z.toy,basis=basis.toy)
```

---

 object

*Optimization of posterior likelihood of hyperparameters*


---

**Description**

Returns the likelihood of a set of hyperparameters given the data. Functions `opt1()` and `opt.gt.1()` find hyperparameters that maximize the relevant likelihood for level 1 and higher levels respectively. Function `object()` returns the expression given by equation 9 in KOH2000, which is minimized `opt1()` and `opt.gt.1()`.

**Usage**

```
object(level, D, z, basis, subsets, hpa)
opt.1(D, z, basis, subsets, hpa.start, give.answers=FALSE, ...)
opt.gt.1(level, D, z, basis, subsets, hpa.start, give.answers=FALSE, ...)
```

**Arguments**

<code>level</code>	level
<code>D</code>	Design matrix for top-level code
<code>z</code>	Data
<code>basis</code>	Basis function
<code>subsets</code>	subsets object
<code>hpa</code>	hyperparameter object
<code>hpa.start</code>	Starting value for hyperparameter object
<code>give.answers</code>	Boolean, with default FALSE meaning to return just the point estimate, and TRUE meaning to return extra information from the call to <code>optim()</code>
<code>...</code>	Extra arguments passed to <code>optim()</code> . A common one would be <code>control=list(trace=100)</code>

**Details**

This function is the object function used in toy optimizers `optimal.hpa()`.

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**See Also**

[genie](#)

**Examples**

```

data(toyapps)
object(level=4, D=D1.toy , z=z.toy,basis=basis.toy,
  subsets=subsets.toy, hpa=hpa.fun.toy(1:19))
object(level=4, D=D1.toy , z=z.toy,basis=basis.toy,
  subsets=subsets.toy, hpa=hpa.fun.toy(3+(1:19)))

# Now a little example of finding optimal hyperparameters in the toy case
# (a bigger example is given on the genie help page)
jj <- list(trace=100,maxit=10)

hpa.toy.level1 <- opt.1(D=D1.toy, z=z.toy, basis=basis.toy,
  subsets=subsets.toy, hpa.start=hpa.toy,control=jj)

hpa.toy.level2 <- opt.gt.1(level=2, D=D1.toy, z=z.toy,
  basis=basis.toy, subsets=subsets.toy,
  hpa.start=hpa.toy.level1, control=jj)

hpa.toy.level3 <- opt.gt.1(level=3, D=D1.toy, z=z.toy,
  basis=basis.toy, subsets=subsets.toy,
  hpa.start=hpa.toy.level2, control=jj)

hpa.toy.level4 <- opt.gt.1(level=4, D=D1.toy, z=z.toy,
  basis=basis.toy, subsets=subsets.toy,
  hpa.start=hpa.toy.level3, control=jj)

```

---

 Pi

*Kennedy's Pi notation*


---

**Description**

Evaluates Kennedy's  $\prod$  product

**Usage**

Pi(hpa, i, j)

**Arguments**

hpa	Hyperparameter object
i	subscript
j	superscript

**Details**

This function evaluates Kennedy's  $\prod$  product, but with the additional feature that  $\prod_i^j = 0$  if  $i > j + 1$ . This seems to work in practice.



**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
Pi(hpa.toy,1,2)
Pi(hpa.toy,2,2)
Pi(hpa.toy,3,2)
Pi(hpa.toy,4,2)
```

---

subsets.fun

*Generate and test subsets*

---

**Description**

Create a list of subsets (`subsets.fun()`); or, given a list of subsets, test for correct inclusion (`is.nested()`), or strict inclusion (`is.strict()`).

**Usage**

```
is.nested(subsets)
is.strict(subsets)
subsets.fun(n, levels = 4, prob = 0.7)
```

**Arguments**

subsets	In <code>is.nested()</code> , a list of subsets to be tested
n	Number of observations in the lowest level (ie level 1, the fastest code)
levels	Number of levels
prob	Probability of choosing an observation at level $n + 1$ given that there is one at the same place at level $n$

**Author(s)**

Robin K. S. Hankin (`subsets.fun()`); Peter Dalgaard (via R-help)

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
is.nested(subsets.fun(20)) # Should be TRUE

data(toyapps)
stopifnot(is.nested(subsets.toy))
```

---

subset\_maker

*Create a simple subset object*


---

**Description**

Given an integer vector whose  $i^{\text{th}}$  element is the number of runs at level  $i$ , return a subset object in echelon form.

**Usage**

```
subset_maker(x)
```

**Arguments**

`x`                    A vector of integers

**Details**

In this context, `x` being in “echelon form” means that

- `x` is consistent in the sense of passing `is.consistent()`
- For each  $i$ , `x[[i]] = 1:n` for some  $n$ .

**Value**

A list object suitable for use as a subset object

**Author(s)**

Robin K. S. Hankin

**See Also**

[is.consistent](#), [is.nested](#), [is.strict](#)

**Examples**

```
subset_maker(c(10,4,3))

is.nested(subset_maker(c(4,9,6))) #should be FALSE
is.nested(subset_maker(c(9,6,4))) #should be TRUE
```

---

tee.fun	<i>Returns generalized distances</i>
---------	--------------------------------------

---

**Description**

Returns generalized distances from a point to the design matrix as per equation 10

**Usage**

```
tee.fun(x, D1, subsets, hpa)
```

**Arguments**

x	Point in parameter space
D1	Design matrix for level 1 code
subsets	subsets object
hpa	Hyperparameter object

**Details**

See equation 10

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O'Hagan 2000. "Predicting the output from a complex computer code when fast approximations are available" *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
tee.fun(x=1:3, D1=D1.toy, subsets=subsets.toy, hpa=hpa.toy)
```

---

toyapps

*Toy datasets for approximator package*

---

## Description

Toy datasets that illustrate the package.

## Usage

```
data(toyapps)
D1.toy
hpa.toy
z.toy
subsets.toy
betas.toy
```

## Format

The toy example is a case with four levels.

The `D1.toy` matrix is 20 rows of code run points, corresponding to the observations of the level 1 code. It has three columns, one per parameter.

`hpa.toy` is a hyperparameter object. It is a list of three elements: `sigmas`, `B`, and `rhos`.

`subsets.toy` is a list of four elements. Element  $i$  corresponds to the rows of `D1.toy` at which level  $i$  has been observed.

`z.toy` is a four element list. Each element is a vector; element  $i$  corresponds to observations of level  $i$ . The lengths will match those of `subsets.toy`.

`betas.toy` is a matrix of coefficients.

### **Brief description of toy functions fully documented under their own manpage**

Function `generate.toy.observations()` creates new toy datasets with any number of observations and code runs.

Function `basis.toy()` is an example of a basis function

Function `hpa.fun.toy()` creates a hyperparameter object such as `phi.toy` in a form suitable for passing to the other functions in the library.

**See the helpfiles listed in the “see also” section below**

## Details

All toy datasets are documented here. There are also several toy functions that are needed for a toy problem; these are documented separately (they are too diverse to document fully in a single manpage). Nevertheless a terse summary for each toy function is provided on this page. All toy functions in the package are listed under “See Also”.

## Author(s)

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O’Hagan 2000. “Predicting the output from a complex computer code when fast approximations are available” *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)

is.consistent(subsets.toy , z.toy)

generate.toy.observations(D1.toy, subsets.toy, basis.toy, hpa.toy, betas.toy)
```

---

V.fun.app

*Variance matrix*


---

**Description**

Given a design matrix, a subsets object and a hyperparameter object, return the variance matrix. The “app” of the function name means “approximator”, to distinguish it from function `V.fun()` of the calibrator package.

**Usage**

```
V.fun.app(D1, subsets, hpa)
```

**Arguments**

D1	Design matrix for level 1 code
subsets	Subsets object
hpa	Hyperparameter object

**Author(s)**

Robin K. S. Hankin

**References**

M. C. Kennedy and A. O’Hagan 2000. “Predicting the output from a complex computer code when fast approximations are available” *Biometrika*, 87(1): pp1-13

**Examples**

```
data(toyapps)
V.fun.app(D1.toy, subsets.toy, hpa.toy)
```

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