# Package 'ebnm'

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**Title** Solve the Empirical Bayes Normal Means Problem

**URL** https://github.com/stephenslab/ebnm

**BugReports** https://github.com/stephenslab/ebnm/issues

**Description** Provides simple, fast, and stable functions to fit the normal means model using empirical Bayes. For available models and details, see function ebnm(). A comprehensive introduction to the package is provided by Willwerscheid and Stephens (2021) <arXiv:2110.00152>.

**License** GPL (>= 3)

**NeedsCompilation** no

**Depends** R (>= 3.3.0)

**Imports** stats, methods, ashr, mixsqp, truncnorm, trust, horseshoe, deconvolveR, magrittr, rlang, dplyr, ggplot2

**Suggests** testthat, numDeriv, REBayes

**RoxygenNote** 7.1.2

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# R topics documented:



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ebnm *Solve the EBNM problem*

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## Description

Solves the empirical Bayes normal means (EBNM) problem using a specified family of priors. For a comprehensive introduction to the package, see the paper cited in **References** below.

## Usage

```
ebnm(
  x,
  s = 1,
 prior_family = c("point_normal", "point_laplace", "point_exponential", "normal",
    "horseshoe", "normal_scale_mixture", "unimodal", "unimodal_symmetric",
  "unimodal_nonnegative", "unimodal_nonpositive", "npmle", "deconvolver", "ash"),
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL,
  ...
)

output_default()

output_all()
```

## Arguments

| | |
|---|---|
| x | A vector of observations. Missing observations (NAs) are not allowed. |
| s | A vector of standard errors (or a scalar if all are equal). Standard errors may not be exactly zero, and missing standard errors are not allowed. Two prior families have additional restrictions: when horseshoe priors are used, errors must be |

homoskedastic; and since function deconv in package deconvolveR takes $z$-scores, all standard errors must be equal to 1 when the "deconvolver" family is used.

prior_family — A character string that specifies the prior family $G$. See "Details" below.

mode — A scalar specifying the mode of the prior $g$ or "estimate" if the mode is to be estimated from the data. This parameter is ignored by the NPMLE and deconvolveR prior family.

scale — A scalar or vector specifying the scale parameter(s) of the prior or "estimate" if the scale parameters are to be estimated from the data. The interpretation of scale depends on the prior family. For normal and point-normal families, it is a scalar specifying the standard deviation of the normal component. For point-Laplace and point-exponential families, it is a scalar specifying the scale parameter of the Laplace or exponential component. For the horseshoe family, it corresponds to $s\tau$ in the usual parametrization of the horseshoe distribution. For the NPMLE and deconvolveR prior family, it is a scalar specifying the distance between support points. For all other prior families, which are implemented using the function ash in package ashr, it is a vector specifying the parameter mixsd to be passed to ash or "estimate" if mixsd is to be chosen by ebnm. (Note that ebnm chooses mixsd differently from ashr. To use the ashr grid, set scale = "estimate" and pass in gridmult as an additional parameter. See ash for defaults and details.)

g_init — The prior distribution $g$. Usually this is left unspecified (NULL) and estimated from the data. However, it can be used in conjuction with fix_g = TRUE to fix the prior (useful, for example, to do computations with the "true" $g$ in simulations). If g_init is specified but fix_g = FALSE, g_init specifies the initial value of $g$ used during optimization. For non-parametric priors, this has the side effect of fixing the mode and scale parameters. If g_init is supplied, it should be an object of class normalmix for normal, point-normal, scale mixture of normals, and deconvolveR prior families, as well as for the NPMLE; class laplacemix for point-Laplace families; class gammamix for point-exponential families; class horseshoe for horseshoe families; and class unimix for unimodal_ families.

fix_g — If TRUE, fix the prior $g$ at g_init instead of estimating it.

output — A character vector indicating which values are to be returned. Function output_default() provides the default return values, while output_all() lists all possible return values. See "Value" below.

optmethod — A string specifying which optimization function is to be used. Options include "nlm", "lbfgsb" (which calls optim with method = "L-BFGS-B"), and "trust" (which calls into package trust). Other options are "nohess_nlm", "nograd_nlm", and "nograd_lbfgsb", which use numerical approximations rather than exact expressions for the Hessian and (for the latter two) the gradient. The default option is "nohess_nlm". Since all non-parametric families rely upon external packages, this parameter is only available for parametric families (point-normal, point-Laplace, point-exponential, and normal).

control — A list of control parameters to be passed to the optimization function. optimize is used for normal and horseshoe prior families, while nlm is used for parametric families unless parameter optmethod specifies otherwise. nlm is also used for

the deconvolveR prior family. For ash families (including scale mixtures of normals, the NPMLE, and all unimodal_ families), function mixsqp in package mixsqp is the default.

... Additional parameters. When a unimodal_ prior family is used, these parameters are passed to function ash in package ashr. When the "deconvolver" family is used, they are passed to function deconv in package deconvolveR. Although it does not call into ashr, the scale mixture of normals family accepts parameter gridmult for purposes of comparison. When gridmult is set, an ashr-style grid will be used instead of the default ebnm grid. In all other cases, additional parameters are ignored.

## Details

Given vectors of data x and standard errors s, ebnm solves the "empirical Bayes normal means" (EBNM) problem for various choices of prior family. The model is

$$x_j|\theta_j, s_j \sim N(\theta_j, s_j^2)$$

$$\theta_j \sim g \in G,$$

where $g$, which is referred to as the "prior distribution" for $\theta$, is to be estimated from among some specified family of prior distributions $G$. Several options for $G$ are implemented, some parametric and others non-parametric; see below for examples.

Solving the EBNM problem involves two steps. First, $g \in G$ is estimated via maximum marginal likelihood:

$$\hat{g} := \arg\max_{g \in G} L(g),$$

where

$$L(g) := \prod_j \int p(x_j|\theta_j, s_j) g(d\theta_j).$$

Second, posterior distributions $p(\theta_j|x_j, s_j, \hat{g})$ and/or summaries such as posterior means and posterior second moments are computed.

Implemented prior families include:

point_normal The family of mixtures where one component is a point mass at $\mu$ and the other is a normal distribution centered at $\mu$.

point_laplace The family of mixtures where one component is a point mass at zero and the other is a double-exponential distribution.

point_exponential The family of mixtures where one component is a point mass at zero and the other is a (nonnegative) exponential distribution.

normal The family of normal distributions.

horseshoe The family of horseshoe distributions.

normal_scale_mixture The family of scale mixtures of normals.

unimodal The family of all unimodal distributions.

unimodal_symmetric The family of symmetric unimodal distributions.

unimodal_nonnegative The family of unimodal distributions with support constrained to be greater than the mode.

`unimodal_nonpositive` The family of unimodal distributions with support constrained to be less than the mode.

`npmle` The family of all distributions.

`deconvolver` A non-parametric exponential family with a natural spline basis. Like `npmle`, there is no unimodal assumption, but whereas `npmle` produces spiky estimates for $g$, `deconvolver` estimates are much more regular. See `deconvolveR-package` for details and references.

## Value

An `ebnm` object. Depending on the argument to `output`, the object is a list containing elements:

`data` A data frame containing the observations `x` and standard errors `s`.

`posterior` A data frame of summary results (posterior means, standard deviations, second moments, and local false sign rates).

`fitted_g` The fitted prior $\hat{g}$ (an object of class `normalmix`, `laplacemix`, `gammamix`, `unimix`, or `horseshoe`).

`log_likelihood` The optimal log likelihood attained, $L(\hat{g})$.

`posterior_sampler` A function that can be used to produce samples from the posterior. For all prior families other than the horseshoe, the sampler takes a single parameter `nsamp`, the number of posterior samples to return per observation. Since `ebnm_horseshoe` returns an MCMC sampler, it additionally takes parameter `burn`, the number of burn-in samples to discard.

## Functions

- `output_default`: Lists the default return values.
- `output_all`: Lists all valid return values.

## References

Jason Willwerscheid and Matthew Stephens (2021). `ebnm`: an `R` Package for solving the empirical Bayes normal means problem using a variety of prior families. arXiv, 2110.00152, 2021.

## See Also

A plotting method is available for `ebnm` objects: see `plot.ebnm`.

Calling functions `ebnm_point_normal`, `ebnm_point_laplace`, `ebnm_point_exponential`, `ebnm_normal`, `ebnm_horseshoe`, `ebnm_normal_scale_mixture`, `ebnm_unimodal`, `ebnm_unimodal_symmetric`, `ebnm_unimodal_nonnegative`, `ebnm_unimodal_nonpositive`, `ebnm_npmle`, `ebnm_deconvolver`, and `ebnm_ash` is equivalent to calling `ebnm` with `prior_family` set accordingly.

## Examples

```
theta <- c(rep(0, 100), rexp(100))
s <- 1
x <- theta + rnorm(200, 0, s)

# The following are equivalent:
pn.res <- ebnm(x, s, prior_family = "point_normal")
```

```
pn.res <- ebnm_point_normal(x, s)

# Inspect results:
pn.res$log_likelihood
plot(pn.res)

# Fix the scale parameter:
pl.res <- ebnm_point_laplace(x, s, scale = 1)
pl.res$fitted_g$scale

# Estimate the mode:
normal.res <- ebnm_normal(x, s, mode = "estimate")
normal.res$fitted_g$mean

# Use an initial g (this fixes mode and scale for ash priors):
normalmix.res <- ebnm_normal_scale_mixture(x, s, g_init = pn.res$fitted_g)

# Fix g and get different output:
g_init <- pn.res$fitted_g
pn.res <- ebnm_point_normal(x, s, g_init = g_init, fix_g = TRUE,
                            output = "posterior_sampler")
pn.res <- ebnm_point_normal(x, s, g_init = g_init, fix_g = TRUE,
                            output = output_all())

# Sample from the posterior:
pn.postsamp <- pn.res$posterior_sampler(nsamp = 100)

# Examples of usage of control parameter:
#  point_normal uses nlm:
pn.res <- ebnm_point_normal(x, s, control = list(print.level = 1))
#  unimodal uses mixsqp:
unimodal.res <- ebnm_unimodal(x, s, control = list(verbose = TRUE))
```

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`ebnm_point_normal` *Solve the EBNM problem using a specified family of priors*

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## Description

Each of the functions listed below solves the empirical Bayes normal means (EBNM) problem using a specified family of priors. Calling function `ebnm_xxx` is equivalent to calling function `ebnm` with argument `prior_family = "xxx"`. For details about the model, see `ebnm` or the paper cited in **References** below.

## Usage

```
ebnm_point_normal(
  x,
  s = 1,
  mode = 0,
```

```
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL
)

ebnm_point_laplace(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL
)

ebnm_point_exponential(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL
)

ebnm_normal(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL
)

ebnm_horseshoe(
  x,
  s = 1,
  scale = "estimate",
```

```
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL
)

ebnm_normal_scale_mixture(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_unimodal(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_unimodal_symmetric(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_unimodal_nonnegative(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
```

```
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_unimodal_nonpositive(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_ash(
  x,
  s = 1,
  mode = 0,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  control = NULL,
  ...
)

ebnm_npmle(
  x,
  s = 1,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
  output = output_default(),
  optmethod = NULL,
  control = NULL,
  ...
)

ebnm_deconvolver(
  x,
  s = 1,
  scale = "estimate",
  g_init = NULL,
  fix_g = FALSE,
```

```
  output = output_default(),
  control = NULL,
  ...
)
```

## Arguments

| | |
|---|---|
| x | A vector of observations. Missing observations (NAs) are not allowed. |
| s | A vector of standard errors (or a scalar if all are equal). Standard errors may not be exactly zero, and missing standard errors are not allowed. Two prior families have additional restrictions: when horseshoe priors are used, errors must be homoskedastic; and since function deconv in package deconvolveR takes $z$-scores, all standard errors must be equal to 1 when the "deconvolver" family is used. |
| mode | A scalar specifying the mode of the prior $g$ or "estimate" if the mode is to be estimated from the data. This parameter is ignored by the NPMLE and deconvolveR prior family. |
| scale | A scalar or vector specifying the scale parameter(s) of the prior or "estimate" if the scale parameters are to be estimated from the data. The interpretation of scale depends on the prior family. For normal and point-normal families, it is a scalar specifying the standard deviation of the normal component. For point-Laplace and point-exponential families, it is a scalar specifying the scale parameter of the Laplace or exponential component. For the horseshoe family, it corresponds to $s\tau$ in the usual parametrization of the horseshoe distribution. For the NPMLE and deconvolveR prior family, it is a scalar specifying the distance between support points. For all other prior families, which are implemented using the function ash in package ashr, it is a vector specifying the parameter mixsd to be passed to ash or "estimate" if mixsd is to be chosen by ebnm. (Note that ebnm chooses mixsd differently from ashr. To use the ashr grid, set scale = "estimate" and pass in gridmult as an additional parameter. See ash for defaults and details.) |
| g_init | The prior distribution $g$. Usually this is left unspecified (NULL) and estimated from the data. However, it can be used in conjuction with fix_g = TRUE to fix the prior (useful, for example, to do computations with the "true" $g$ in simulations). If g_init is specified but fix_g = FALSE, g_init specifies the initial value of $g$ used during optimization. For non-parametric priors, this has the side effect of fixing the mode and scale parameters. If g_init is supplied, it should be an object of class normalmix for normal, point-normal, scale mixture of normals, and deconvolveR prior families, as well as for the NPMLE; class laplacemix for point-Laplace families; class gammamix for point-exponential families; class horseshoe for horseshoe families; and class unimix for unimodal_ families. |
| fix_g | If TRUE, fix the prior $g$ at g_init instead of estimating it. |
| output | A character vector indicating which values are to be returned. Function output_default() provides the default return values, while output_all() lists all possible return values. See "Value" below. |
| optmethod | A string specifying which optimization function is to be used. Options include "nlm", "lbfgsb" (which calls optim with method = "L-BFGS-B"), and |

"trust" (which calls into package trust). Other options are "nohess_nlm", "nograd_nlm", and "nograd_lbfgsb", which use numerical approximations rather than exact expressions for the Hessian and (for the latter two) the gradient. The default option is "nohess_nlm". Since all non-parametric families rely upon external packages, this parameter is only available for parametric families (point-normal, point-Laplace, point-exponential, and normal).

control — A list of control parameters to be passed to the optimization function. optimize is used for normal and horseshoe prior families, while nlm is used for parametric families unless parameter optmethod specifies otherwise. nlm is also used for the deconvolveR prior family. For ash families (including scale mixtures of normals, the NPMLE, and all unimodal_ families), function mixsqp in package mixsqp is the default.

... — Additional parameters. When a unimodal_ prior family is used, these parameters are passed to function ash in package ashr. When the "deconvolver" family is used, they are passed to function deconv in package deconvolveR. Although it does not call into ashr, the scale mixture of normals family accepts parameter gridmult for purposes of comparison. When gridmult is set, an ashr-style grid will be used instead of the default ebnm grid. In all other cases, additional parameters are ignored.

## Details

Implemented prior families include:

ebnm_point_normal The family of mixtures where one component is a point mass at $\mu$ and the other is a normal distribution centered at $\mu$.

ebnm_point_laplace The family of mixtures where one component is a point mass at zero and the other is a double-exponential distribution.

ebnm_point_exponential The family of mixtures where one component is a point mass at zero and the other is a (nonnegative) exponential distribution.

ebnm_normal The family of normal distributions.

ebnm_horseshoe The family of horseshoe distributions.

ebnm_normal_scale_mixture The family of scale mixtures of normals.

ebnm_unimodal The family of all unimodal distributions.

ebnm_unimodal_symmetric The family of symmetric unimodal distributions.

ebnm_unimodal_nonnegative The family of unimodal distributions with support constrained to be greater than the mode.

ebnm_unimodal_nonpositive The family of unimodal distributions with support constrained to be less than the mode.

ebnm_npmle The family of all distributions.

ebnm_deconvolver A non-parametric exponential family with a natural spline basis. Like npmle, there is no unimodal assumption, but whereas npmle produces spiky estimates for $g$, deconvolver estimates are much more regular. See deconvolveR-package for details and references.

## Value

An ebnm object. Depending on the argument to output, the object is a list containing elements:

data A data frame containing the observations x and standard errors s.

posterior A data frame of summary results (posterior means, standard deviations, second moments, and local false sign rates).

fitted_g The fitted prior $\hat{g}$ (an object of class normalmix, laplacemix, gammamix, unimix, or horseshoe).

log_likelihood The optimal log likelihood attained, $L(\hat{g})$.

posterior_sampler A function that can be used to produce samples from the posterior. For all prior families other than the horseshoe, the sampler takes a single parameter nsamp, the number of posterior samples to return per observation. Since ebnm_horseshoe returns an MCMC sampler, it additionally takes parameter burn, the number of burn-in samples to discard.

## References

Jason Willwerscheid and Matthew Stephens (2021). ebnm: an R Package for solving the empirical Bayes normal means problem using a variety of prior families. arXiv, 2110.00152, 2021.

## See Also

ebnm

## Examples

```
theta <- c(rep(0, 100), rexp(100))
s <- 1
x <- theta + rnorm(200, 0, s)

# The following are equivalent:
pn.res <- ebnm(x, s, prior_family = "point_normal")
pn.res <- ebnm_point_normal(x, s)

# Inspect results:
pn.res$log_likelihood
plot(pn.res)

# Fix the scale parameter:
pl.res <- ebnm_point_laplace(x, s, scale = 1)
pl.res$fitted_g$scale

# Estimate the mode:
normal.res <- ebnm_normal(x, s, mode = "estimate")
normal.res$fitted_g$mean

# Use an initial g (this fixes mode and scale for ash priors):
normalmix.res <- ebnm_normal_scale_mixture(x, s, g_init = pn.res$fitted_g)

# Fix g and get different output:
g_init <- pn.res$fitted_g
```

```
pn.res <- ebnm_point_normal(x, s, g_init = g_init, fix_g = TRUE,
                            output = "posterior_sampler")
pn.res <- ebnm_point_normal(x, s, g_init = g_init, fix_g = TRUE,
                            output = output_all())

# Sample from the posterior:
pn.postsamp <- pn.res$posterior_sampler(nsamp = 100)

# Examples of usage of control parameter:
#  point_normal uses nlm:
pn.res <- ebnm_point_normal(x, s, control = list(print.level = 1))
#  unimodal uses mixsqp:
unimodal.res <- ebnm_unimodal(x, s, control = list(verbose = TRUE))
```

---

`gammamix` *Constructor for gammamix class*

---

## Description

Creates a finite mixture of gamma distributions.

## Usage

```
gammamix(pi, shape, scale, shift = rep(0, length(pi)))
```

## Arguments

| | |
|---|---|
| `pi` | A vector of mixture proportions. |
| `shape` | A vector of shape parameters. |
| `scale` | A vector of scale parameters. |
| `shift` | A vector of shift parameters. |

## Value

An object of class `gammamix` (a list with elements `pi`, `shape`, `scale`, and `shift`, described above).

## horseshoe *Constructor for horseshoe class*

### Description

Creates a horseshoe prior (see Carvalho, Polson, and Scott (2010)). The horseshoe is usually parametrized as $\theta_i \sim N(0, s^2\tau^2\lambda_i^2)$, $\lambda_i \sim \text{Cauchy}^+(0, 1)$, with $s^2$ the variance of the error distribution. We use a single parameter `scale`, which corresponds to $s\tau$ and thus does not depend on the error distribution.

### Usage

```
horseshoe(scale)
```

### Arguments

| | |
|---|---|
| `scale` | The scale parameter (must be a scalar). |

### Value

An object of class `horseshoe` (a list with a single element `scale`, described above).

## laplacemix *Constructor for laplacemix class*

### Description

Creates a finite mixture of Laplace distributions.

### Usage

```
laplacemix(pi, mean, scale)
```

### Arguments

| | |
|---|---|
| `pi` | A vector of mixture proportions. |
| `mean` | A vector of means. |
| `scale` | A vector of scale parameters. |

### Value

An object of class `laplacemix` (a list with elements `pi`, `mean`, and `scale`, described above).

`plot.ebnm` *Plot an ebnm object*

## Description

Given a fitted ebnm object, produces a plot of posterior means vs. observations.

## Usage

```
## S3 method for class 'ebnm'
plot(x, remove_abline = FALSE, ...)
```

## Arguments

| | |
|---|---|
| x | The fitted ebnm object. |
| remove_abline | To better illustrate shrinkage effects, the plot will include the line $y = x$ by default. If remove_abline = TRUE, then this line will not be drawn. |
| ... | Additional parameters to be passed to ggplot2 function geom_point. |

## Details

An object of class ggplot is returned, so that the plot can be customized in the usual ggplot2 fashion.

## Value

A ggplot object.

## Examples

```
theta <- c(rep(0, 100), rexp(100))
s <- 1
x <- theta + rnorm(200, 0, s)
ebnm.res <- ebnm(x, s)
plot(ebnm.res)

# Customize plot:
library(ggplot2)
plot(ebnm.res, color = "blue", remove_abline = TRUE) +
  theme_bw() +
  labs(x = "Simulated data")
```

print.ebnm *Print an ebnm object*

## Description

The print method for class ebnm.

## Usage

```
## S3 method for class 'ebnm'
print(x, ...)
```

## Arguments

| | |
|---|---|
| x | The fitted ebnm object. |
| ... | Not used. Included for consistency as an S3 method. |

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