Package 'gldrm'

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Type Package

Title Generalized Linear Density Ratio Models

Version 1.5

Description Fits a generalized linear density ratio model (GLDRM).

A GLDRM is a semiparametric generalized linear model.

In contrast to a GLM, which assumes a particular exponential family distribution, the GLDRM uses a semiparametric likelihood to estimate the reference distribution. The reference distribution may be any discrete, continuous, or mixed exponential family distribution. The model parameters, which include both the regression coefficients and the cdf of the unspecified reference distribution, are estimated by maximizing a semiparametric likelihood. Regression coefficients are estimated with no loss of efficiency, i.e. the asymptotic variance is the same as if the true exponential family distribution were known.

Huang (2014) <doi:10.1080/01621459.2013.824892>. Huang and Rathouz (2012) <doi:10.1093/biomet/asr075>. Rathouz and Gao (2008) <doi:10.1093/biostatistics/kxn030>.

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Author Michael Wurm [aut, cre], Paul Rathouz [aut]

Maintainer Michael Wurm < wurm@uwalumni.com>

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beta.control Control arguments for β update algorithm

Description

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This function returns control arguments for the β update algorithm. Each argument has a default value, which will be used unless a different value is provided by the user.

Usage

```
beta.control(eps = 1e-10, maxiter = 1, maxhalf = 10)
```

Arguments

| eps | Convergence threshold. The update has converged when the relative change in log-likelihood between iterations is less than eps. Only applies if maxiter>1. |
|---------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| maxiter | Maximum number of iterations allowed. |
| maxhalf | Maximum number of half steps allowed per iteration if log-likelihood does not improve. |

Value

Object of S3 class "betaControl", which is a list of control arguments.

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| To. Control arguments for fo update digorithm | f0.control | Control arguments for f0 update algorithm | |
|-----------------------------------------------|------------|-------------------------------------------|--|
|-----------------------------------------------|------------|-------------------------------------------|--|

Description

This function returns control arguments for the f_0 update algorithm. Each argument has a default value, which will be used unless a different value is provided by the user.

Usage

```
f0.control(eps = 1e-10, maxiter = 1000, maxhalf = 20, maxlogstep = 2)
```

Arguments

| eps | Convergence threshold. The update has converged when the relative change in |
|-----|----------------------------------------------------------------------------------|
| | log-likelihood between iterations is less than eps. absolute change is less than |

thesh.

maxiter Maximum number of iterations allowed.

maxhalf Maximum number of half steps allowed per iteration if log-likelihood does not

improve between iterations.

maxlogstep Maximum optimization step size allowed on the log(f0) scale.

Value

Object of S3 class "f0Control", which is a list of control arguments.

| gldrm Fits a generalized linear density ratio model (GLDRM) | |
|-------------------------------------------------------------|--|
|-------------------------------------------------------------|--|

Description

A GLDRM is a semiparametric generalized linear model. In contrast to a GLM, which assumes a particular exponential family distribution, the GLDRM uses a semiparametric likelihood to estimate the reference distribution. The reference distribution may be any discrete, continuous, or mixed exponential family distribution. The model parameters, which include both the regression coefficients and the cdf of the unspecified reference distribution, are estimated by maximizing a semiparametric likelihood. Regression coefficients are estimated with no loss of efficiency, i.e. the asymptotic variance is the same as if the true exponential family distribution were known.

Usage

```
gldrm(formula, data = NULL, link = "identity", mu0 = NULL,
  offset = NULL, gldrmControl = gldrm.control(),
  thetaControl = theta.control(), betaControl = beta.control(),
  f0Control = f0.control())
```

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Arguments

formula An object of class "formula".

data An optional data frame containing the variables in the model.

link Link function. Can be a character string to be passed to the make.link function

in the stats package (e.g. "identity", "logit", or "log"). Alternatively, link can be a list containing three functions named linkfun, linkinv, and mu.eta. The first is the link function. The second is the inverse link function. The third is the derivative of the inverse link function. All three functions must be vectorized.

mu0 Mean of the reference distribution. The reference distribution is not unique un-

less its mean is restricted to a specific value. This value can be any number within the range of observed values, but values near the boundary may cause numerical instability. This is an optional argument with mean(y) being the de-

fault value.

offset Known component of the linear term. Offset must be passed through this argu-

ment - offset terms in the formula will be ignored. value and covariate values. If sampling weights are a function of both the response value and covariates, then sampprobs must be a $n \times q$ matrix, where n is the number of observations and q is the number of unique observed values in the response vector. If sampling weights do not depend on the covariate values, then sampprobs may alternatively be passed as a vector of length n. All values must be nonnegative and are

assumed to correspond to the sorted response values in increasing order.

gldrmControl Optional control arguments. Passed as an object of class "gldrmControl", which

is constructed by the gldrm.control function. See gldrm.control documen-

tation for details.

thetaControl Optional control arguments for the theta update procedure. Passed as an object

of class "thetaControl", which is constructed by the theta.control function.

See theta.control documentation for details.

betaControl Optional control arguments for the beta update procedure. Passed as an object

of class "betaControl", which is constructed by the beta.control function. See

beta.control documentation for details.

f0Control Optional control arguments for the f0 update procedure. Passed as an object

of class "f0Control", which is constructed by the f0.control function. See

f0. control documentation for details.

Details

The arguments linkfun, linkinv, and mu.eta mirror the "link-glm" class. Objects of this class can be created with the stats::make.link function.

The "gldrm" class is a list of the following items.

- · conv Logical indicator for whether the gldrm algorithm converged within the iteration limit.
- iter Number of iterations used. A single iteration is a beta update, followed by an f0 update.
- 11ik Semiparametric log-likelihood of the fitted model.
- beta Vector containing the regression coefficient estimates.

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 mu Vector containing the estimated mean response value for each observation in the training data.

- eta Vector containing the estimated linear combination of covariates for each observation.
- f0 Vector containing the semiparametric estimate of the reference distribution, evaluated at the
 observed response values. The values of correspond to the support values, sorted in increasing
 order.
- spt Vector containing the unique observed response values, sorted in increasing order.
- mu0 Mean of the estimated semiparametric reference distribution. The mean of the reference distribution must be fixed at a value in order for the model to be identifiable. It can be fixed at any value within the range of observed response values, but the gldrm function assigns mu0 to be the mean of the observed response values.
- varbeta Estimated variance matrix of the regression coefficients.
- seBeta Standard errors for $\hat{\beta}$. Equal to sqrt(diag(varbeta)).
- seMu Standard errors for $\hat{\mu}$ computed from varbeta.
- seEta Standard errors for $\hat{\eta}$ computed from varbeta.
- theta Vector containing the estimated tilt parameter for each observation. The tilted density function of the response variable is given by

$$f(y|x_i) = f_0(y) \exp(\theta_i y) / \int f_0(u) \exp(\theta_i u) du.$$

• bPrime is a vector containing the mean of the tilted distribution, $b'(\theta_i)$, for each observation. bPrime should match mu, except in cases where theta is capped for numerical stability.

$$b'(\theta_i) = \int u f(u|x_i) du$$

• bPrime2 is a vector containing the variance of the tilted distribution, $b''(\theta_i)$, for each observation.

$$b''(\theta_i) = \int (u - b'(\theta_i))^2 f(u|x_i) du$$

• fTilt is a vector containing the semiparametric fitted probability, $\hat{f}(y_i|x_i)$, for each observation. The semiparametric log-likelihood is equal to

$$\sum_{i=1}^{n} \log \hat{f}(y_i|x_i).$$

- sampprobs If sampling probabilities were passed through the sampprobs argument, then they are returned here in matrix form. Each row corresponds to an observation.
- llikNull Log-likelihood of the null model with no covariates.
- 1r. stat Likelihood ratio test statistic comparing fitted model to the null model. It is calculated as $2 \times (llik llik_0)/(p-1)$. The asymptotic distribution is F(p-1, n-p) under the null hypothesis.
- 1r.pval P-value of the likelihood ratio statistic.

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• fTiltMatrix is a matrix containing the semiparametric density for each observation, i.e. $\hat{f}(y|x_i)$ for each unique y value. This is a matrix with nrow equal to the number of observations and ncol equal to the number of unique response values observed. Only returned if returnfTilt = TRUE in the gldrmControl arguments.

- score.logf0 Score function for log(f0). Only returned if returnf0ScoreInfo = TRUE in the gldrmControl arguments.
- info.logf0 Information matrix for log(f0). Only returned if returnf0ScoreInfo = TRUE in the gldrmControl arguments.
- formula Model formula.
- data Model data frame.
- link Link function. If a character string was passed to the link argument, then this will be an object of class "link-glm". Otherwise, it will be the list of three functions passed to the link argument.

Value

An S3 object of class "gldrm". See details.

Examples

gldrm.control

Control arguments for gldrm algorithm

Description

This function returns control arguments for the gldrm algorithm. Each argument has a default value, which will be used unless a different value is provided by the user.

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Usage

```
gldrm.control(eps = 1e-10, maxiter = 100, returnfTiltMatrix = TRUE,
  returnf0ScoreInfo = FALSE, print = FALSE, betaStart = NULL,
  f0Start = NULL)
```

Arguments

eps

Convergence threshold. The fitting algorithm has converged when the relative change in log-likelihood between iterations is less than eps. A single iteration consists of a beta update followed by an f0 update.

maxiter

Maximum number of iterations allowed.

returnfTiltMatrix

Logical. Return nonparametric fitted probabilities for each observation. This is a matrix with nrow equal to the number of observations and ncol equal to the number of unique response values observed.

returnf0ScoreInfo

Logical. If TRUE, the score and information for log(f0) are returned as compo-

nents of the "gldrm" object.

print Logical. If TRUE, the relative change in the log-likelihood will be printed after

each iteration.

betaStart Optional vector of starting values for beta. If the call to gldrm contains a for-

mula, the values of betaStart should correspond to the columns of the model

matrix.

f0Start Optional vector of starting values for f0. The length of the vector should be the

number of unique values in the response, and the vector should correspond to these values sorted in increasing order. The starting values will be scaled to sum

to one and tilted to have mean mu0. All values should be strictly positive.

Value

Object of S3 class "gldrmControl", which is a list of control arguments.

gldrmCI

Confidence intervals for gldrm coefficients

Description

Calculates a Wald, likelihood ratio, or score confidence interval for a single gldrm coefficient. Also calculates upper or lower confidence bounds. Wald confidence intervals and bounds are calculated from the standard errors which are available from the gldrm model fit. For likelihood ratio and score intervals and bounds, a bisection search method is used, which takes longer to run.

Usage

```
gldrmCI(gldrmFit, term, test = c("Wald", "LRT", "Score"), level = 0.95,
  type = c("2-sided", "lb", "ub"), eps = 1e-10, maxiter = 100)
```

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Arguments

| gldrmFit | A gldrm model fit. Must be an S3 object of class "gldrm", returned from the gldrm function. |
|----------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| term | Character string containing the name of the coefficient of interest. The coefficient names are the names of the beta component of the fitted model object. They can also be obtained from the printed model output. Usually the names match the formula syntax, but can be more complicated for categorical variables and interaction terms. |
| test | Character string for the type confidence interval. Options are "Wald", "LRT" (for likelihood ratio), and "Score". |
| level | Confidence level of the interval. Should be between zero and one. |
| type | Character string containing "2-sided" for a two-sided confidence interval, "lb" for a lower bound, or "ub" for an upper bound. |
| eps | Convergence threshold. Only applies for test = "LRT" and test = "Score". Convergence is reached when likelihood ratio p-value is within eps of the target p-value, based on the level of the test. For example, a two-sided 95% confidence interval has target p-value of 0.025 for both the upper and lower bounds. A 95% confidence bound has target p-value 0.05. |
| maxiter | The maximum number of bisection method iterations for likelihood ratio intervals or bounds. For two-sided intervals, maxiter iterations are allowed for each bound. |

Value

An S3 object of class 'gldrmCI', which is a list of the following items.

- term Coefficient name.
- test Type of interval or bound Wald or likelihood ratio.
- level Confidence level.
- type Type of interval or bound two-sided, upper bound, or lower bound.
- cilo/cihi Upper and lower interval bounds. One one of the two applies for confidence bounds.
- iterlo/iterhi Number of bisection iterations used. Only applies for likelihood ratio intervals and bounds.
- pvallo/pvalhi For likelihood ratio intervals and bounds, the p-value at convergence is reported.
- conv Indicator for whether the confidence interval limit or bound converged.

Examples

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```
### Wald 95% confidence interval for Sepal.Width
ci <- gldrmCI(fit, "Sepal.Width", test="Wald", level=.95, type="2-sided")
ci</pre>
```

gldrmLRT

Likelihood ratio test for nested models

Description

Performs a likelihood ratio F-test between nested gldrm models. The F-statistic is calculated as $2 \times (llik - llik_0)/r$, where r is the difference is the number of parameters between the full and null models. The F-statistic has degrees of freedom r and n-p, where n is the number of observations and p is the number of parameters in the full model.

Usage

```
gldrmLRT(gldrmFit, gldrmNull)
```

Arguments

gldrmFit The full model. Must be an object of S3 class 'gldrm' returned from the gldrm

function.

gldrmNull The sub-model being tested under the null hypotheses. Must be an object of S3

class 'gldrm' returned from the gldrm function.

Value

An S3 object of class 'gldrmLRT', containing numerator and denominator degrees of freedom, an F-statistic, and a p-value.

Examples

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| gldrmPIT | Confidence intervals for gldrm coefficients | |
|----------|---------------------------------------------|--|
|----------|---------------------------------------------|--|

Description

Plots and returns the randomized probability inverse transform of a fitted gldrm.

Usage

```
gldrmPIT(gldrmFit, nbreaks = 7, cex.main = NULL, cex.lab = NULL,
    cex.axis = NULL)
```

Arguments

| gldrmFit | A gldrm model fit. Must be an S3 object of class "gldrm", returned from the |
|----------|--------------------------------------------------------------------------------------------|
| | gldrm function. The matrix of semiparametric tilted probabilities must be re- |
| | turned, which is done by fitting gldrm with gldrmControl = gldrm.control(returnfTiltMatrix |
| | = TRUE). |
| nbreaks | Number of breaks in the histogram. |
| cex.main | Text size for main titles. |
| cex.lab | Text size for axis labels. |
| cex.axis | Text size for axis numbers. |

Details

The probability inverse transform is defined generally as $\hat{F}(y|x)$, which is the fitted conditional cdf of each observation evaluated at the observed response value. In the case of gldrm, the fitted cdf is descrete, so we draw a random value from a uniform distribution on the interval $(\hat{F}(y|x), \hat{F}(y-|x))$, where y- is the next largest observed support less than y (or -Infinity if y is the minimum support value). The output and plots generated by this function will vary slightly each time it is called (unless the random number generator seed is set beforehand).

Value

Randomized robability inverse transform as a vector. Also plots the histogram and uniform QQ plot.

Examples

predict.gldrm 11

| predict.gldrm Predict method for a gldrm object |
|-------------------------------------------------|
|-------------------------------------------------|

Description

Obtains predicted probabilities, predicted class, or linear predictors.

Usage

```
## S3 method for class 'gldrm'
predict(object, newdata = NULL, type = c("link", "response",
   "terms", "fTilt"), se.fit = FALSE, offset = NULL, ...)
```

Arguments

| object | S3 object of class "gldrm", returned from the gldrm function. |
|---------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| newdata | Optional data frame. If NULL, fitted values will be obtained for the training data. |
| type | The type of prediction required. Type "link" returns the linear predictor. Type "response" returns the fitted mean. Type "terms" returns a matrix giving the fitted values of each term in the model formula on the linear predictor scale. Type "fTilt" returns a matrix containing the fitted nonparametric distribution for each observation. Each row of the matrix corresponds to an observation in newdata, and each column corresponds to a unique response value in the training data. |
| se.fit | Logical. If TRUE, standard errors are also returned. Does not apply for type = "fTilt". |
| offset | Optional offset vector. Only used if newdata is not NULL. |
| | Not used. Additional predict arguments. |

Value

The object returned depends on type.

| | print.gldrm | Print summary of gldrm fit | |
|--|-------------|----------------------------|--|
|--|-------------|----------------------------|--|

Description

Prints fitted coefficients and standard errors, along with a likelihood ratio test against the null model.

Usage

```
## S3 method for class 'gldrm'
print(x, digits = 3, ...)
```

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Arguments

| Χ | S3 object of class "gldrm", returned from the gldrm function. |
|--------|---------------------------------------------------------------|
| digits | Number of digits for rounding. |
| | Unused. Additional arguments for print method. |

print.gldrmCI

Print confidence interval

Description

Print method for gldrmCI objects.

Usage

```
## S3 method for class 'gldrmCI'
print(x, digits = 3, ...)
```

Arguments

x An S3 object of class 'gldrmCI'.
digits Number of digits for rounding.

... Not used. Additional arguments for print method.

print.gldrmLRT

Print likelihood ratio test results

Description

Print method for gldrmLRT objects. Prints results of a likelihood ratio F-test between nested models.

Usage

```
## S3 method for class 'gldrmLRT'
print(x, digits = 3, ...)
```

Arguments

x S3 object of class 'gldrmLRT', returned from the gldrmLRT function.

digits Number of digits for rounding.

... Not used. Additional arguments for print method.

theta.control 13

| theta.control Control arguments for θ update algorithm |
|---------------------------------------------------------------|
|---------------------------------------------------------------|

Description

This function returns control arguments for the θ update algorithm. Each argument has a default value, which will be used unless a different value is provided by the user.

Usage

```
theta.control(eps = 1e-10, maxiter = 100, maxhalf = 20, maxtheta = 500,
    logit = TRUE, logsumexp = FALSE)
```

Arguments

| eps | Convergence threshold for theta updates. Convergence is evaluated separately for each observation. An observation has converged when the difference between $b'(\theta)$ and μ is less than epsTheta. |
|-----------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| maxiter | Maximum number of iterations. |
| maxhalf | Maximum number of half steps allowed per iteration if the convergence criterion does not improve. |
| maxtheta | Absolute value of theta is not allowed to exceed maxtheta. |
| logit | Logical for whether logit transformation should be used. Use of this stabilizing transformation appears to be faster in general. Default is TRUE. |
| logsumexp | Logical argument for whether log-sum-exp trick should be used. This may improve numerical stability at the expense of computational time. |

Value

Object of S3 class "thetaControl", which is a list of control arguments.

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