

Package ‘nlsr’

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Type Package

Title Functions for Nonlinear Least Squares Solutions - Updated 2022

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Description Provides tools for working with nonlinear least squares problems.

For the estimation of models reliable and robust tools than nls(), where the Gauss-Newton method frequently stops with 'singular gradient' messages. This is accomplished by using, where possible, analytic derivatives to compute the matrix of derivatives and a stabilization of the solution of the estimation equations. Tools for approximate or externally supplied derivative matrices are included. Bounds and masks on parameters are handled properly.

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Encoding UTF-8

Depends R (>= 3.5)

Imports digest

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coef.nlsr*coef.nlsr*

Descriptionprepare and display result of `nlsr` computations

Usage

```
## S3 method for class 'nlsr'  
coef(object, ...)
```

Arguments

object	an object of class <code>nlsr</code>
...	additional data needed to evaluate the modeling functions Default FALSE

Details

The set of possible controls to set is as follows

Author(s)

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dex	<i>dex</i>
-----	------------

Description

Calculate expression for derivative calculations. Converts input to an expression suitable for use in `nlsDeriv` and related functions.

Usage

```
dex(x, do_substitute = NA, verbose = FALSE)
```

Arguments

x	An expression represented in a variety of ways. See Details.
do_substitute	Whether to use the expression passed as x, or to evaluate it and use its value.
verbose	Print messages describing the process.

Details

If `do_substitute` is NA, the following rules are used:

An attempt is made to evaluate x. If that fails, the expression is used.

If the evaluation succeeds and the value is a character vector, it is parsed.

If the value is not a character vector and the expression is a single name, the value is used.

Otherwise, the expression is used.

Once the expression is determined it may be simplified, by extracting the language object from a length-one expression vector, or the right-hand-side from a formula.

Normally a warning will be issued if x is a formula containing a left-hand side. To suppress this, wrap the formula in `expression()`, or pass it as a character string to be parsed.

value

An expression or language object suitable as input to [nlsDeriv](#) and related functions.

Author(s)

Duncan Murdoch

Examples

```
aa <- dex(~ x^2)
aa
str(aa)
bb <- dex(expression(x^2))
bb
str(bb)
cc <- dex("x^2")
cc
str(cc)
```

findSubexprs

findSubexprs

Description

Try to find the sub-expressions in `expr ??`

Usage

```
findSubexprs(expr, simplify = FALSE, tag = ".expr", verbose = FALSE, ...)
```

Arguments

<code>expr</code>	An expression represented in a variety of ways. See Details.
<code>simplify</code>	The environment in which simplifications are stored.
<code>tag</code>	to be attached to the returned object(s)??
<code>verbose</code>	If TRUE, then diagnostic output will be printed as derivatives and simplifications are recognized.
<code>...</code>	Additional arguments

fitted.nlsr

fitted.nlsr

Description

prepare and display fits of nlsr computations

Usage

```
## S3 method for class 'nlsr'  
fitted(object = NULL, data = parent.frame(), ...)
```

Arguments

object	an object of class nlsr
data	a data frame with the date for which fits are wanted ?? how do we guarantee it is the data used to fit the model Or do we need a different approach?
...	additional data needed to evaluate the modeling functions Default FALSE

Author(s)

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isCALL

isCALL Test if argument is a call

Description

isCALL

Test if argument is a call

Usage

```
isCALL(x, name)
```

Arguments

x	object to be tested
name	??need to document better – is it a character string?

isMINUSONE

isMINUSONE

Description

isMINUSONE

Usage

`isMINUSONE(x)`

Arguments

x object to be tested

isONE

isONE

Description

Test if argument is one

Usage

`isONE(x)`

Arguments

x object to be tested

isZERO

isZERO

Description

Test if argument is zero

Usage

`isZERO(x)`

Arguments

x object to be tested

*jaback**jaback*

Description

approximate Jacobian via forward differences

Usage

```
jaback(pars, resfn = NULL, bdmsk = NULL, resbest = NULL, ndstep = 1e-07, ...)
```

Arguments

pars	a named numeric vector of parameters to the model
resfn	a function to compute a vector of residuals
bdmsk	?? do we need it? Default is NULL
resbest	If supplied, a vector of the residuals at the parameters pars to save re-evaluation.
ndstep	A tolerance used to alter parameters to compute numerical approximations to derivatives. Default 1e-7.
...	Extra information needed to compute the residuals

Author(s)

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*jaccentral**jaccentral*

Description

approximate Jacobian via central differences. Note this needs two evaluations per parameter, but generally gives much better approximation of the derivatives.

Usage

```
jaccentral(  
  pars,  
  resfn = NULL,  
  bdmsk = NULL,  
  resbest = NULL,  
  ndstep = 1e-07,  
  ...  
)
```

Arguments

<code>pars</code>	a named numeric vector of parameters to the model
<code>resfn</code>	a function to compute a vector of residuals
<code>bdmsk</code>	?? do we need it? Default is <code>NULL</code>
<code>resbest</code>	If supplied, a vector of the residuals at the parameters <code>pars</code> to save re-evaluation.
<code>ndstep</code>	A tolerance used to alter parameters to compute numerical approximations to derivatives. Default <code>1e-7</code> .
...	Extra information needed to compute the residuals

Author(s)

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jafwd

jafwd

Description

approximate Jacobian via forward differences

Usage

```
jafwd(pars, resfn = NULL, bdmsk = NULL, resbest = NULL, ndstep = 1e-07, ...)
```

Arguments

<code>pars</code>	a named numeric vector of parameters to the model
<code>resfn</code>	a function to compute a vector of residuals
<code>bdmsk</code>	?? do we need it? Default is <code>NULL</code>
<code>resbest</code>	If supplied, a vector of the residuals at the parameters <code>pars</code> to save re-evaluation.
<code>ndstep</code>	A tolerance used to alter parameters to compute numerical approximations to derivatives. Default <code>1e-7</code> .
...	Extra information needed to compute the residuals

Author(s)

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*jand**jand*

Description

approximate Jacobian via numDeriv::jacobian

Usage

```
jand(pars, resfn = NULL, bdmsk = NULL, resbest = NULL, ndstep = 1e-07, ...)
```

Arguments

pars	a named numeric vector of parameters to the model
resfn	a function to compute a vector of residuals
bdmsk	?? do we need it? Default is NULL
resbest	If supplied, a vector of the residuals at the parameters <code>pars</code> to save re-evaluation.
ndstep	A tolerance used to alter parameters to compute numerical approximations to derivatives. Default 1e-7.
...	Extra information needed to compute the residuals

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

*model2rjfun**model2rjfun*

Description

These functions create functions to evaluate residuals or sums of squares at particular parameter locations.

Usage

```
model2rjfun(modelformula, pvec, data = NULL, jacobian = TRUE, testresult = TRUE, ...)
SSmod2rjfun(modelformula, pvec, data = NULL, jacobian = TRUE, testresult = TRUE, ...)
model2ssgrfun(modelformula, pvec, data = NULL, gradient = TRUE,
               testresult = TRUE, ...)
modelexpr(fun)
```

Arguments

<code>modelformula</code>	A formula describing a nonlinear regression model.
<code>pvec</code>	A vector of parameters.
<code>data</code>	A dataframe, list or environment holding data used in the calculation.
<code>jacobian</code>	Whether to compute the Jacobian matrix.
<code>testresult</code>	Whether to test the function by evaluating it at <code>pvec</code> .
<code>...</code>	Dot arguments, that is, arguments that may be supplied by <code>name = value</code> to supply information needed to compute specific quantities in the model. @details If <code>pvec</code> does not have names, the parameters will have names generated in the form ' <code>p_<n></code> ', e.g. <code>p_1</code> , <code>p_2</code> . Names that appear in <code>pvec</code> will be taken to be parameters of the model.
	The <code>data</code> argument may be a dataframe, list or environment, or <code>NULL</code> . If it is not an environment, one will be constructed using the components of <code>data</code> with parent environment set to be the environment of <code>modelformula</code> .
	<code>SSmod2rjfun</code> returns a function with header <code>function(prm)</code> , which evaluates the residuals (and if <code>jacobian</code> is <code>TRUE</code> the Jacobian matrix) of the selfStart model (the <code>rhs</code> is used) at <code>prm</code> . The residuals are defined to be the right hand side of <code>modelformula</code> minus the left hand side. Note that the selfStart model used in the model formula must be available (i.e., loaded). If this function is called from <code>n1xb()</code> then the control element <code>japprox</code> must be @section value <code>model2rjfun</code> returns a function with header <code>function(prm)</code> , which evaluates the residuals (and if <code>jacobian</code> is <code>TRUE</code> the Jacobian matrix) of the model at <code>prm</code> . The residuals are defined to be the right hand side of <code>modelformula</code> minus the left hand side.
	<code>model2ssgrfun</code> returns a function with header <code>function(prm)</code> , which evaluates the sum of squared residuals (and if <code>gradient</code> is <code>TRUE</code> the gradient vector) of the model at <code>prm</code> .
	<code>modelexpr</code> returns the expression used to calculate the vector of residuals (and possibly the Jacobian) used in the previous functions.
<code>gradient</code>	Whether to compute the gradient vector.
<code>fun</code>	A function produced by one of <code>model2rjfun</code> or <code>model2ssgrfun</code> .

keyword

nonlinear

Author(s)

John Nash and Duncan Murdoch

See Also

[nls](#)

Examples

```

y <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443, 38.558,
      50.156, 62.948, 75.995, 91.972)

tt <- seq_along(y) # for testing

mydata <- data.frame(y = y, tt = tt)
f <- y ~ b1/(1 + b2 * exp(-1 * b3 * tt))
p <- c(b1 = 1, b2 = 1, b3 = 1)
rjfn <- model2rjfun(f, p, data = mydata)
rjfn(p)
myexp <- modelexpr(rjfn)
cat("myexp:"); print(myexp)

ssgrfn <- model2ssgrfun(f, p, data = mydata)
ssgrfn(p)

```

newDeriv

*newDeriv***Description**

Define a new derivative expression

Usage

```
newDeriv (expr, deriv, derivEnv = sysDerivs)
```

Arguments

- | | |
|-----------------------|---|
| <code>expr</code> | An expression represented in a variety of ways. |
| <code>deriv</code> | An expression giving the derivative of the function call in <code>expr</code> . |
| <code>derivEnv</code> | The environment in which to evaluate (??) these |

newSimplification

*newSimplification***Description**

Define a new simplification expression

Usage

```
newSimplification(expr, test, simplification, do_eval = FALSE,
                  simpEnv = sysSimplifications)
```

Arguments

<code>expr</code>	An expression represented in a variety of ways.
<code>test</code>	?? what is this
<code>simplification</code>	?? what is this
<code>do_eval</code>	??evaluate the result
<code>simpEnv</code>	the environment in which the simplification is carried out

nlfb*nlfb: nonlinear least squares modeling by functions*

Description

A simplified and hopefully robust alternative to finding the nonlinear least squares minimizer that causes 'formula' to give a minimal residual sum of squares.

Usage

```
nlfb(
  start,
  resfn,
  jacfn = NULL,
  trace = FALSE,
  lower = -Inf,
  upper = Inf,
  weights = NULL,
  data = NULL,
  ctrlcopy = FALSE,
  control = list(),
  ...
)
```

Arguments

<code>start</code>	a numeric vector with all elements present e.g., <code>start=c(b1=200, b2=50, b3=0.3)</code> ?? does it need names?
<code>resfn</code>	A function that evaluates the residual vector for computing the elements of the sum of squares function at the set of parameters <code>start</code> . Where this function is created by actions on a formula or expression in <code>nlxn</code> , this residual vector will be created by evaluation of the 'model - data', rather than the conventional 'data - model' approach. The sum of squares is the same.
<code>jacfn</code>	A function that evaluates the Jacobian of the sum of squares function, that is, the matrix of partial derivatives of the residuals with respect to each of the parameters. If <code>NULL</code> (default), uses an approximation. The Jacobian MUST be returned as the attribute "gradient" of this function, allowing <code>jacfn</code> to have the same name and be the same code block as <code>resfn</code> , which may permit some efficiencies of computation.

trace	TRUE for console output during execution
lower	a vector of lower bounds on the parameters. If a single number, this will be applied to all. Default -Inf.
upper	a vector of upper bounds on the parameters. If a single number, this will be applied to all parameters. Default Inf.
weights	A vector of fixed weights. The objective function that will be minimized is the sum of squares where each residual is multiplied by the square root of the corresponding weight. Default NULL implies unit weights.
data	a data frame of variables used by resfn and jacfn to compute the required residuals and Jacobian.
ctrlcopy	If TRUE use control supplied as is. Saves reprocessing controls.
control	a list of control parameters. See nlsr.control().
...	additional data needed to evaluate the modeling functions

Details

nlfb is particularly intended to allow for the resolution of very ill-conditioned or else near zero-residual problems for which the regular nls() function is ill-suited.

This variant uses a qr solution without forming the sum of squares and cross products $t(J)$

Neither this function nor n1xb have provision for parameter scaling (as in the parscale control of optim and package optimx). This would be more tedious than difficult to introduce, but does not seem to be a priority feature to add.

Value

A list of the following items:

coefficients A named vector giving the parameter values at the supposed solution.

ssquares The sum of squared residuals at this set of parameters.

resid The residual vector at the returned parameters.

jacobian The jacobian matrix (partial derivatives of residuals w.r.t. the parameters) at the returned parameters.

feval The number of residual evaluations (sum of squares computations) used.

jeval The number of Jacobian evaluations used.

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

Examples

```
library(nlsr)
# Scaled Hobbs problem
shobbs.res <- function(x){ # scaled Hobbs weeds problem -- residual
  # This variant uses looping
  if(length(x) != 3) stop("shobbs.res -- parameter vector n!=3")
```

```

y <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443,
      38.558, 50.156, 62.948, 75.995, 91.972)
tt <- 1:12
res <- 100.0*x[1]/(1+x[2]*10.*exp(-0.1*x[3]*tt)) - y
}
shobbs.jac <- function(x) { # scaled Hobbs weeds problem -- Jacobian
  jj <- matrix(0.0, 12, 3)
  tt <- 1:12
  yy <- exp(-0.1*x[3]*tt)
  zz <- 100.0/(1+10.*x[2]*yy)
  jj[tt,1] <- zz
  jj[tt,2] <- -0.1*x[1]*zz*zz*yy
  jj[tt,3] <- 0.01*x[1]*zz*zz*yy*x[2]*tt
  attr(jj, "gradient") <- jj
  jj
}
st <- c(b1=2, b2=1, b3=1) # a default starting vector (named!)
anlf1bm <- nlfb(start=st, resfn=shobbs.res, jacfn=shobbs.jac, lower=c(2,0,0),
upper=c(2,6,3))
anlf1bm
## Short output
pshort(anlf1bm)
anlf2bm <- nlfb(start=st, resfn=shobbs.res, jacfn=shobbs.jac, lower=c(2,0,0),
upper=c(2,6,9))
anlf2bm
## Short output
pshort(anlf2bm)

```

nlsDeriv*nlsDeriv Functions to take symbolic derivatives.***Description**

Compute derivatives of simple expressions symbolically, allowing user-specified derivatives.

Usage

```

nlsDeriv(expr, name, derivEnv = sysDerivs, do_substitute = FALSE, verbose = FALSE, ...)
codeDeriv(expr, namevec, hessian = FALSE, derivEnv = sysDerivs,
          do_substitute = FALSE, verbose = FALSE, ...)
fnDeriv(expr, namevec, args = all.vars(expr), env = environment(expr),
        do_substitute = FALSE, verbose = FALSE, ...)

```

Arguments

<code>expr</code>	An expression represented in a variety of ways. See Details.
<code>name</code>	The name of the variable with respect to which the derivative will be computed.
<code>derivEnv</code>	The environment in which derivatives are stored.
<code>do_substitute</code>	If TRUE, use <code>substitute</code> to get the expression passed as <code>expr</code> , otherwise evaluate it.
<code>verbose</code>	If TRUE, then diagnostic output will be printed as derivatives and simplifications are recognized.
<code>...</code>	Additional parameters which will be passed to <code>codeDeriv</code> from <code>fnDeriv</code> , and to <code>nlsSimplify</code> from <code>nlsDeriv</code> and <code>codeDeriv</code> .
<code>namevec</code>	Character vector giving the variable names with respect to which the derivatives will be taken.
<code>hessian</code>	Logical indicator of whether the 2nd derivatives should also be computed.
<code>args</code>	Desired arguments for the function. See Details below.
<code>env</code>	The environment to be attached to the created function. If NULL, the caller's frame is used.

Details

Functions `nlsDeriv` and `codeDeriv` are designed as replacements for the `stats` package functions `D` and `deriv` respectively, though the argument lists do not match exactly.

The `nlsDeriv` function computes a symbolic derivative of an expression or language object. Known derivatives are stored in `derivEnv`; the default `sysDerivs` contains expressions for all of the derivatives recognized by `deriv`, but in addition allows differentiation with respect to any parameter where it makes sense. It also allows the derivative of `abs` and `sign`, using an arbitrary choice of 0 at the discontinuities.

The `codeDeriv` function computes an expression for efficient calculation of the expression value together with its gradient and optionally the Hessian matrix.

The `fnDeriv` function wraps the `codeDeriv` result in a function. If the `args` are given as a character vector (the default), the arguments will have those names, with no default values. Alternatively, a custom argument list with default values can be created using `alist`; see the example below.

The `expr` argument will be converted to a language object using `dex` (but note the different default for `do_substitute`). Normally it should be a formula with no left hand side, e.g. `~ x^2`, or an expression vector e.g. `expression(x, x^2, x^3)`, or a language object e.g. `quote(x^2)`. In `codeDeriv` and `fnDeriv` the expression vector must be of length 1.

The `newDeriv` function is used to define a new derivative. The `expr` argument should match the header of the function as a call to it (e.g. as in the help pages), and the `deriv` argument should be an expression giving the derivative, including calls to `D(arg)`, which will not be evaluated, but will be substituted with partial derivatives of that argument with respect to `name`. See the examples below.

If `expr` or `deriv` is missing in a call to `newDeriv()`, it will return the currently saved derivative record from `derivEnv`. If `name` is missing in a call to `nlsDeriv` with a function call, it will print a message describing the derivative formula and return NULL.

To handle functions which act differently if a parameter is missing, code the default value of that parameter to `.MissingVal`, and give a derivative that is conditional on `missing()` applied to that parameter. See the derivatives of “-” and “+” in the file `derivs.R` for an example.

`@section value`

If `expr` is an expression vector, `nlsDeriv` and `nlsSimplify` return expression vectors containing the response. For formulas or language objects, a language object is returned.

`codeDeriv` always returns a language object.

`fnDeriv` returns a closure (i.e. a function).

`nlsDeriv` returns the symbolic derivative of the expression.

`newDeriv` with `expr` and `deriv` specified is called for the side effect of recording the derivative in `derivEnv`. If `expr` is missing, it will return the list of names of functions for which derivatives are recorded. If `deriv` is missing, it will return its record for the specified function.

`@section note #'` `newDeriv(expr, deriv, ...)` will issue a warning if a different definition for the derivative exists in the derivative table.

`@author Duncan Murdoch`

`@seealso deriv`

`@examples newDeriv() newDeriv(sin(x)) nlsDeriv(~ sin(x+y), "x")`

`f <- function(x) x^2 newDeriv(f(x), 2*x*D(x)) nlsDeriv(~ f(abs(x)), "x")`

`nlsDeriv(~ pnorm(x, sd=2, log = TRUE), "x") fnDeriv(~ pnorm(x, sd = sd, log = TRUE), "x") f <- fnDeriv(~ pnorm(x, sd = sd, log = TRUE), "x", args = alist(x =, sd = 2)) f f(1) 100*(f(1.01) - f(1))`
`# Should be close to the gradient`

`# The attached gradient attribute (from f(1.01)) is # meaningless after the subtraction.`

`# Multiple point example xvals <- c(1, 3, 4.123) print(f(xvals)) # Getting a hessian matrix f2 <- ~ (x-2)^3*y - y^2 mydf2 <- fnDeriv(f2, c("x", "y"), hessian=TRUE) # display the resulting function print(mydf2) x <- c(1, 2) y <- c(0.5, 0.1) evalmydf2 <- mydf2(x, y) print(evalmydf2) # the first index of the hessian attribute is the point at which we want the hessian hmat1 <- as.matrix(attr(evalmydf2, "hessian")[1,,]) print(hmat1) hmat2 <- as.matrix(attr(evalmydf2, "hessian")[2,,]) print(hmat2)`

`@section keyword math, nonlinear`

Description

`nlsr-package`

Usage

`nlsr()`

Details

This package includes methods for solving nonlinear least squares problems specified by a modeling expression and given a starting vector of named parameters. Note: You must provide an expression of the form `lhs ~ rhsexpression` so that the residual expression `rhsexpression - lhs` can be computed. The expression can be enclosed in quotes, and this seems to give fewer difficulties with R. Data variables must already be defined, either within the parent environment or else in the dot-arguments. Other symbolic elements in the modeling expression must be standard functions or else parameters that are named in the start vector.

The main functions in `nlsr` are:

`nlfb` Nash variant of the Marquardt procedure for nonlinear least squares, with bounds constraints, using a residual and optionally Jacobian described as R functions.

`nlxb` Nash variant of the Marquardt procedure for nonlinear least squares, with bounds constraints, using an expression to describe the residual via an R modeling expression. The Jacobian is computed via symbolic differentiation.

`wrapnlsr` Uses `nlxb` to solve nonlinear least squares then calls `nls()` to create an object of type `nls`.

`model2rjfun` returns a function with header `function(prm)`, which evaluates the residuals (and if `jacobian` is `TRUE` the Jacobian matrix) of the model at `prm`. The residuals are defined to be the right hand side of `modelformula` minus the left hand side.

`model2ssgrfun` returns a function with header `function(prm)`, which evaluates the sum of squared residuals (and if `gradient` is `TRUE` the gradient vector) of the model at `prm`.

`modelexpr` returns the expression used to calculate the vector of residuals (and possibly the Jacobian) used in the previous functions.

Author(s)

John C Nash and Duncan Murdoch

References

Nash, J. C. (1979, 1990) _Compact Numerical Methods for Computers. Linear Algebra and Function Minimisation._ Adam Hilger./Institute of Physics Publications

Nash, J. C. (2014) _Nonlinear Parameter Optimization Using R Tools._ Wiley

`nlsr.control`

nlsr.control

Description

set and provide defaults of controls for package `nlsr`

Usage

`nlsr.control(control)`

Arguments

control A list of controls. If missing, the defaults are provided. See below. If a named control is provided, e.g., via a call `ctrllist<- nlsr.control(japprox="jand")`, then that value is substituted for the default of the control in the FULL list of controls that is returned.

NOTE: at 2022-6-17 there is NO CHECK FOR VALIDITY

The set of possible controls to set is as follows, and is returned.

Value

femax INTEGER limit on the number of evaluations of residual function Default 10000.

japprox CHARACTER name of the Jacobian approximation to use Default NULL, since we try to use analytic gradient

jemax INTEGER limit on the number of evaluations of the Jacobian Default 5000

lamda REAL initial value of the Marquardt parameter Default 0.0001 Note: mis-spelling as in JNWMS, kept as historical serendipity.

lamdec REAL multiplier used to REDUCE lamda ($0 < \text{lamdec} < \text{laminc}$) Default 4, so $\text{lamda} \leftarrow \text{lamda} * (\text{lamdec}/\text{laminc})$

laminc REAL multiplier to INCREASE lamda ($1 < \text{laminc}$ Default 10

ndstep REAL stepsize for numerical Jacobian approximation Default 1e-7

numjac LOGICAL If TRUE use a numerical approximation to Jacobian. Default FALSE

offset REAL A value used to test for numerical equality, i.e. a and b are taken equal if $(a + \text{offset}) == (b + \text{offset})$ Default 100.

phi REAL Factor used to add unit Marquardt stabilization matrix in Nash modification of LM method. Default 1. choices

psi REAL Factor used to add scaled Marquardt stabilization matrix in Nash modification of LM method. Default 0.

rofftest LOGICAL If TRUE, perform (safeguarded) relative offset convergence test Default TRUE

smallsstest LOGICAL If TRUE tests sum of squares and terminates if very small ??describe Default TRUE

stepredn REAL Factor used to reduce the stepsize in a Gauss-Newton algorithm (Hartley's method). 0 means NO backtrack. Default 0.

watch LOGICAL to provide a pause at the end of each iteration for user to monitor progress. Default FALSE

prlvl INTEGER The higher the value, the more intermediate output is provided. Default 0

scaleOffset a positive constant to be added to the denominator sum-of-squares in the relative offset convergence criteria. Default 0.

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

nlsSimplify*nlsSimplify*

Description

Try to simplify an expression re: nonlinear least squares

Usage

```
nlsSimplify(expr, simpEnv = sysSimplifications, verbose = FALSE)
```

Arguments

- | | |
|----------------------|--|
| <code>expr</code> | An expression represented in a variety of ways. See Details. |
| <code>simpEnv</code> | The environment in which simplifications are stored. |
| <code>verbose</code> | If TRUE, then diagnostic output will be printed as derivatives and simplifications are recognized. |
-

nlxb*nlxb: nonlinear least squares modeling by formula*

Description

A simplified and hopefully robust alternative to finding the nonlinear least squares minimizer that causes 'formula' to give a minimal residual sum of squares.

Usage

```
nlxb(  
  formula,  
  data = parent.frame(),  
  start,  
  trace = FALSE,  
  lower = NULL,  
  upper = NULL,  
  weights = NULL,  
  control = list(),  
  ...  
)
```

Arguments

<code>formula</code>	The modeling formula. Looks like ' <code>y~b1/(1+b2*exp(-b3*T))'</code>
<code>data</code>	a data frame containing data for variables used in the formula that are NOT the parameters. This data may also be defined in the parent frame i.e., 'global' to this function
<code>start</code>	MUST be a named vector with all elements present e.g., <code>start=c(b1=200, b2=50, b3=0.3)</code>
<code>trace</code>	TRUE for console output during execution
<code>lower</code>	a vector of lower bounds on the parameters. If a single number, this will be applied to all parameters Default NULL.
<code>upper</code>	a vector of upper bounds on the parameters. If a single number, this will be applied to all parameters. Default NULL.
<code>weights</code>	A vector of fixed weights. The objective function that will be minimized is the sum of squares where each residual is multiplied by the square root of the corresponding weight. Default NULL implies unit weights.
<code>control</code>	a list of control parameters. See <code>nlsr.control()</code> .
<code>...</code>	additional data needed to evaluate the modeling functions

Details

`nlxb` is particularly intended to allow for the resolution of very ill-conditioned or else near zero-residual problems for which the regular `nls()` function is ill-suited.

This variant uses a qr solution without forming the sum of squares and cross products $t(J)$

Neither this function nor `nlfb` have provision for parameter scaling (as in the `parscale` control of `optim` and package `optimx`). This would be more tedious than difficult to introduce, but does not seem to be a priority feature to add.

There are many controls, and some of them are important for `nlxb`. In particular, if the derivatives needed for developing the Jacobian are NOT in the derivatives table, then we must supply code elsewhere as specified by the control `japprox`. This was originally just for numerical approximations, with the character strings "jafwd", "jaback", "jacentral" and "jand" leading to the use of a forward, backward, central or package `numDeriv` approximation. However, it is also possible to use code embedded in the residual function created using the `formula`. This is particularly useful for `selfStart` models, and we use the character string "SSJac" to point to such Jacobian code. Note how the starting parameter vector is found using the `getInitial` function from the `stats` package as in an example below.

Value

list of solution elements

`resid` = weighted residuals at the proposed solution `jacobian` = Jacobian matrix at the proposed solution `feval` = residual function evaluations used to reach solution from starting parameters `jeval` = Jacobian function (or approximation) evaluations used `coefficients` = a named vector of proposed solution parameters `ssquares` = weighted sum of squared residuals (often the deviance) `lower` = lower bounds on parameters `upper` = upper bounds on parameters `maskidx` = vector if indices of fixed (masked) parameters `weights` = specified weights on observations `formula` = the modeling formula `resfn` = the residual function (unweighted) based on the formula

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

Examples

```

library(nlsr)
weed <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443,
         38.558, 50.156, 62.948, 75.995, 91.972)
tt <- 1:12
weeddf <- data.frame(tt, weed)
frm <-
wmodu <- weed ~ b1/(1+b2*exp(-b3*tt)) # Unscaled
## nls from unit start FAILS
start1<-c(b1=1, b2=1, b3=1)
hunls1 <- try(nls(wmodu, data=weeddf, start=start1, trace=FALSE))
if (! inherits(hunls1, "try-error")) print(hunls1) ## else cat("Failure -- try-error\n")
## nlxb from unit start
hunlx1 <- try(nlxb(wmodu, data=weeddf, start=c(b1=1, b2=1, b3=1), trace=FALSE))
if (! inherits(hunlx1, "try-error")) print(hunlx1)

st2h<-c(b1=185, b2=10, b3=.3)
#' hunls2 <- try(nls(wmodu, data=weeddf, start=st2h, trace=FALSE))
if (! inherits(hunls1, "try-error")) print(hunls1) ## else cat("Failure -- try-error\n")
## nlxb from unit start
hunlx1 <- try(nlxb(wmodu, data=weeddf, start=st2h, trace=FALSE))
if (! inherits(hunlx1, "try-error")) print(hunlx1)

# Functional models need to use a Jacobian approximation or external calculation.
# For example, the SSlogis() selfStart model from \code{stats} package.

# nls() needs NO starting value
hSSnls<-try(nls(weed~SSlogis(tt, Asym, xmid, scal), data=weeddf))
summary(hSSnls)
# We need to get the start for nlxb explicitly
stSS <- getInitial(weed ~ SSlogis(tt, Asym, xmid, scal), data=weeddf)
hSSnlx<-try(nlxb(weed~SSlogis(tt, Asym, xmid, scal), data=weeddf, start=stSS))
hSSnlx

# nls() can only bound parameters with algorithm="port"
# and minpack.lm is unreliable in imposing bounds, but nlsr copes fine.
lo<-c(0, 0, 0)
up<-c(190, 10, 2) # Note: start must be admissible.
bnls0<-try(nls(wmodu, data=weeddf, start=st2h,
                lower=lo, upper=up)) # should complain and fail

bnls<-try(nls(wmodu, data=weeddf, start=st2h,
                lower=lo, upper=up, algorith="port"))
summary(bnls)
bnlx<-try(nlxb(wmodu, data=weeddf, start=st2h, lower=lo, upper=up))
bnlx

# nlxb() can also MASK (fix) parameters. The mechanism of maskidx from nls

```

```

# is NO LONGER USED. Instead we set upper and lower parameters equal for
# the masked parameters. The start value MUST be equal to this fixed value.
lo<-c(190, 0, 0) # mask first parameter
up<-c(190, 10, 2)
strt <- c(b1=190, b2=1, b3=1)
mnlx<-try(nlxb(wmodu, start=strt, data=weeddf,
                 lower=lo, upper=up))
mnlx
mnls<-try(nls(wmodu, data=weeddf, start=strt,
                 lower=lo, upper=up, algorith="port"))
summary(mnls)

# Try first parameter masked and see if we get SEs
lo<-c(200, 0, 0) # mask first parameter
up<-c(100, 10, 5)
strt <- c(b1=200, b2=1, b3=1)
mnlx<-try(nlxb(wmodu, start=strt, data=weeddf,
                 lower=lo, upper=up))
mnlx
mnls<-try(nls(wmodu, data=weeddf, start=strt,
                 lower=lo, upper=up, algorith="port"))
summary(mnls)

```

numericDerivR

*numericDerivR: numerically evaluates the gradient of an expression.
All in R*

Description

This version is all in R to replace the C version in package stats

Usage

```
numericDerivR(
  expr,
  theta,
  rho = parent.frame(),
  dir = 1,
  eps = .Machine$double.eps^(1/if (central) 3 else 2),
  central = FALSE
)
```

Arguments

- | | |
|-------|---|
| expr | expression or call to be differentiated. Should evaluate to a numeric vector. |
| theta | character vector of names of numeric variables used in expr. |
| rho | environment containing all the variables needed to evaluate expr. |

dir	numeric vector of directions, typically with values in -1, 1 to use for the finite differences; will be recycled to the length of theta.
eps	a positive number, to be used as unit step size hh for the approximate numerical derivative $(f(x+h)-f(x))/h$ $(f(x+h)-f(x))/h$ or the central version, see central.
central	logical indicating if central divided differences should be computed, i.e., $(f(x+h) - f(x-h)) / 2h$ $(f(x+h)-f(x-h))/2h$. These are typically more accurate but need more evaluations of $f()$.

Value

The value of eval(expr, envir = rho) plus a matrix attribute "gradient". The columns of this matrix are the derivatives of the value with respect to the variables listed in theta.

Examples

```
ex <- expression(a/(1+b*exp(-tt*c)) - weed)
weed <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443,
       38.558, 50.156, 62.948, 75.995, 91.972)
tt <- 1:12
a <- 200; b <- 50; c <- 0.3
dhobb <- numericDerivR(ex, theta=c("a", "b", "c"))
print(dhobb)
# exf <- ~ a/(1+b*exp(-tt*c)) - weed
# Note that a formula doesn't work
# dh1 <- try(numericDerivR(exf, theta=c("a", "b", "c")))
```

Description

Compact display of specified nvec named vector

Usage

```
nvec(vec)
```

Arguments

vec	a named vector of parameters
-----	------------------------------

Value

none (??may want to change that)

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

pctrl *pctrl*

Description

Compact display of specified control vector

Usage

```
pctrl(control)
```

Arguments

control a control list

Value

none (??may want to change that)

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

pnlm0 *pnlm0*

Description

Compact display of specified minpack.lm object x

Usage

```
pnlm0(x)
```

Arguments

x a minpack.lm nlsLM() or nls.lm() result object

Value

none

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

*pnls0**pnls0*

Description

Compact display of specified nls object x

Usage

```
pnls0(x)
```

Arguments

x an nls() result object

Value

none

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

*predict.nlsr**predict.nlsr*

Description

prepare and display predictions from an nlsr model

Usage

```
## S3 method for class 'nlsr'  
predict(object = NULL, newdata = list(), ...)
```

Arguments

object an object of class nlsr
newdata a dataframe containing columns that match the original dataframe used to estimate the nonlinear model in the nlsr object
... additional data needed to evaluate the modeling functions Default FALSE

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

`print.nlsr` *print.nlsr*

Description

prepare and display result of `nlsr` computations

Usage

```
## S3 method for class 'nlsr'
print(x, ...)
```

Arguments

<code>x</code>	an object of class <code>nlsr</code>
<code>...</code>	additional data needed to evaluate the modeling functions Default FALSE

Details

The set of possible controls to set is as follows

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

`pshort` *pshort*

Description

1 line result display of `nlsr` computations

Usage

```
pshort(x)
```

Arguments

<code>x</code>	an object of class <code>nlsr</code>
----------------	--------------------------------------

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

rawres.nlsr

*rawres.nlsr***Description**

prepare and display raw residuals of `nlsr` computations NOTE: we use model - data i.e., rhs - lhs

Usage

```
rawres.nlsr(object = NULL, data = parent.frame(), ...)
```

Arguments

- | | |
|--------|---|
| object | an object of class <code>nlsr</code> |
| data | a data frame with the date for which fits are wanted ?? how do we guarantee it
is the data used to fit the model Or do we need a different approach? |
| ... | additional data needed to evaluate the modeling functions Default FALSE |

Value

A vector of the raw residuals

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

resgr

*resgr***Description**

Computes the gradient of the sum of squares function for nonlinear least squares where `resfn` and `jacfn` supply the residuals and Jacobian

Usage

```
resgr(prm, resfn, jacfn, ...)
```

Arguments

- | | |
|-------|--|
| prm | a numeric vector of parameters to the model |
| resfn | a function to compute a vector of residuals |
| jacfn | a function to compute the Jacobian of the sum of squares |
| ... | Extra information needed to compute the residuals |

Details

?? does it work with approximate Jacobian functions

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

resid.nlsr

resid.nlsr

Description

prepare and display result of `nlsr` computations

Usage

```
## S3 method for class 'nlsr'
resid(object, ...)
```

Arguments

object	an object of class <code>nlsr</code>
...	additional data needed to evaluate the modeling functions

Author(s)

J C Nash nashjc _at_ uottawa.ca
 ### remove _at_export to try to overcome NAMESPACE issue

residuals.nlsr

residuals.nlsr

Description

prepare and display result of `nlsr` computations

Usage

```
## S3 method for class 'nlsr'
residuals(object, ...)
```

Arguments

object	an object of class <code>nlsr</code>
...	additional data needed to evaluate the modeling functions

Author(s)

J C Nash nashjc _at_ uottawa.ca

resss

resss

Description

compute the sum of squares from `resfn` at parameters `prm`

Usage

`resss(prm, resfn, ...)`

Arguments

<code>prm</code>	a named numeric vector of parameters to the model
<code>resfn</code>	a function to compute a vector of residuals
<code>...</code>	Extra information needed to compute the residuals

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

`summary.nlsr`

summary.nlsr

Description

prepare display result of `nlsr` computations - NOT compact output

Usage

```
## S3 method for class 'nlsr'  
summary(object, ...)
```

Arguments

<code>object</code>	an object of class <code>nlsr</code>
<code>...</code>	additional data needed to evaluate the modeling functions

Details

The set of possible controls to set is as follows

Author(s)

J C Nash 2014-7-16 nashjc _at_ uottawa.ca

sysDerivs

sysDerivs

Description

creates a new environment whose parent is emptyenv

Usage

`sysDerivs()`

Format

An object of class `environment` of length 27.

sysSimplifications

sysSimplifications

Description

creates a new environment whose parent is emptyenv

Usage

`sysSimplifications`

Format

An object of class `environment` of length 13.

wrapnlsr

wrapnlsr

Description

Provides class `nls` solution to a nonlinear least squares solution using the Nash Marquardt tools.

Usage

```
wrapnlsr(
  formula = NULL,
  data = NULL,
  start = NULL,
  control = NULL,
  trace = FALSE,
  subset = NULL,
  lower = -Inf,
  upper = Inf,
  weights = NULL,
  ...
)
```

Arguments

formula	The modeling formula. Looks like 'y~b1/(1+b2*exp(-b3*T))'
data	a data frame containing data for variables used in the formula that are NOT the parameters. This data may also be defined in the parent frame i.e., 'global' to this function
start	MUST be a named vector with all elements present e.g., start=c(b1=200, b2=50, b3=0.3)
control	a list of control parameters. See nlsr.control().
trace	TRUE for console output during execution (default FALSE)
subset	an optional vector specifying a subset of observations to be used in the fitting process. NOT used currently by nlxb() or nlfb() and will throw an error if present and not NULL.
lower	a vector of lower bounds on the parameters. If a single number, this will be applied to all parameters Default -Inf.
upper	a vector of upper bounds on the parameters. If a single number, this will be applied to all parameters. Default Inf.
weights	A vector of fixed weights. The objective function that will be minimized is the sum of squares where each residual is multiplied by the square root of the corresponding weight. Default NULL implies unit weights. ???
...	additional data needed to evaluate the modeling functions

Value

A solution object of type nls

Examples

```
library(nlsr)
cat("kvanderpoel.R test of wrapnlsr\n")
x<-c(1,3,5,7)
```

```

y<-c(37.98,11.68,3.65,3.93)
pks28<-data.frame(x=x,y=y)
fit0<-try(nls(y~(a+b*exp(1)^(-c*x)), data=pks28, start=c(a=0,b=1,c=1),
               trace=TRUE))
print(fit0)
fit1<-nlxb(y~(a+b*exp(-c*x)), data=pks28, start=c(a=0,b=1,c=1), trace = TRUE)
print(fit1)
cat("\n\n or better\n")
fit2<-wrapnlsr(y~(a+b*exp(-c*x)), data=pks28, start=c(a=0,b=1,c=1),
                 lower=-Inf, upper=Inf, trace = TRUE)
fit2

weed <- c(5.308, 7.24, 9.638, 12.866, 17.069, 23.192, 31.443,
         38.558, 50.156, 62.948, 75.995, 91.972)
tt <- 1:12
weeddf <- data.frame(tt, weed)
hobbsu <- weed ~ b1/(1+b2*exp(-b3*tt))
st2 <- c(b1=200, b2=50, b3=0.3)
wts <- 0.5^tt # a straight scaling comes via wts <- rep(0.01, 12)
lo <- c(200, 0, 0)
up <- c(1000, 1000, 1000)
whuw2 <- try(wrapnlsr(start=st2, formula=hobbsu, data=weeddf, subset=2:11,
                      weights=wts, trace=TRUE, lower=lo, upper=up))
summary(whuw2)
deviance(whuw2)

```

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